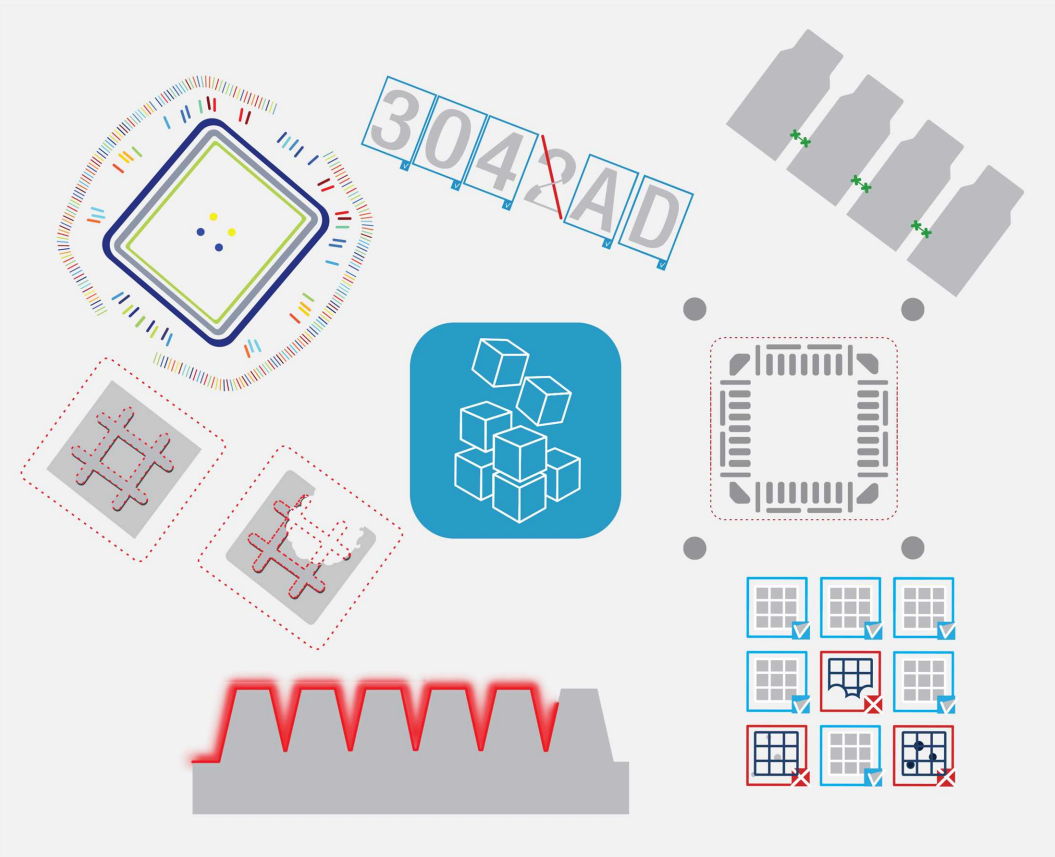


Open eVision

Text and Code Reading Tools



This documentation is provided with Open eVision 2.16.1 (doc build 1156).
www.euresys.com

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1. Dealing with Pixel Containers and Files

1.1. Pixel Container Definition

Images

Open eVision image objects contain image data that represents rectangular images.

Each image object has a data buffer, accessible via a pointer, where pixel values are stored contiguously, row by row.

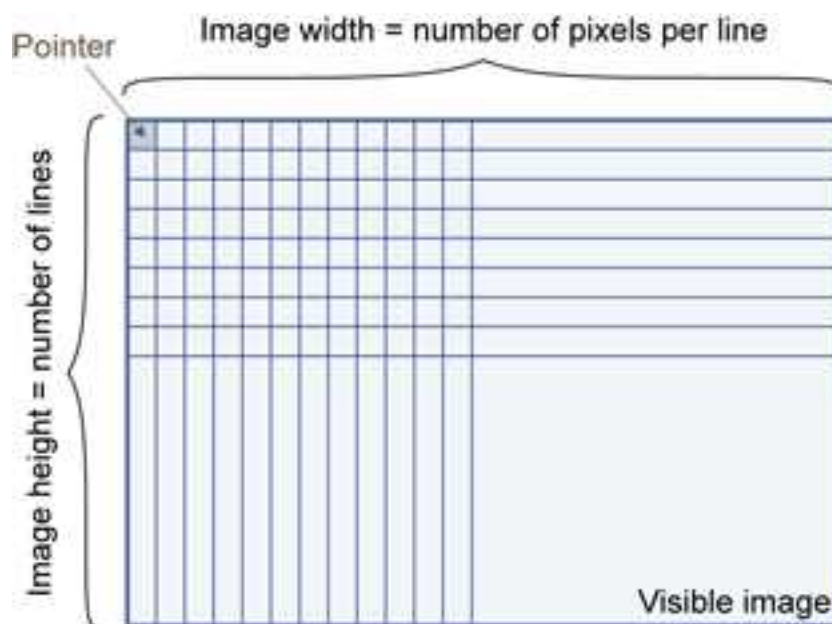


Image main parameters

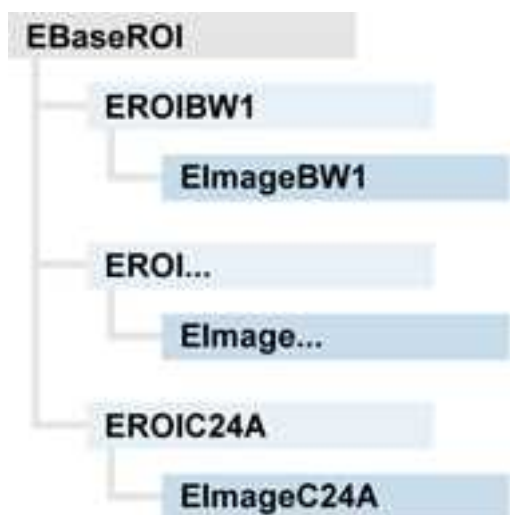
An Open eVision image object has a rectangular array of pixels characterized by [EBaseROI](#) parameters .

- **Width** is the number of columns (pixels) per row of the image.
- **Height** is the number of rows of the image. (Maximum width / height is 32,767 ($2^{15}-1$) in Open eVision 32-bit, and 2,147,483,647 ($2^{31}-1$) in Open eVision 64-bit.)
- **Size** is the width and height.

The **Plane** parameter contains the number of color components. Gray-level images = 1. Color images = 3.

Classes

Image and ROI classes derive from abstract class [EBaseROI](#) and inherit all its properties.



Depth maps

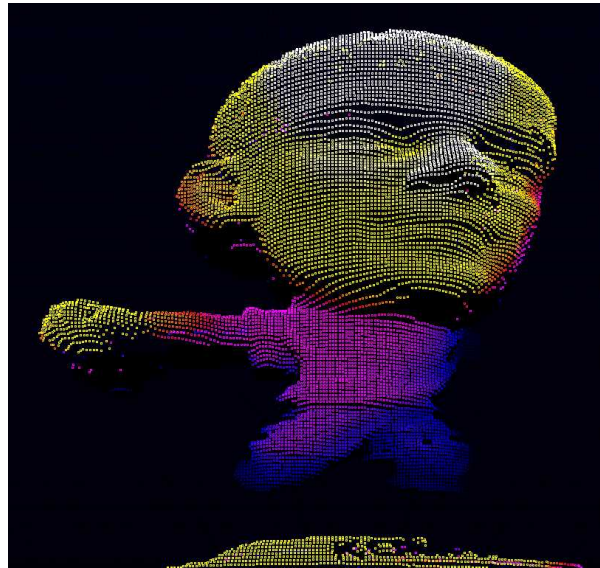
A depth map is a way to represent a 3D object using a 2D grayscale image where each pixel in the image represents a 3D point.



The pixel coordinates are the representation of the X and Y coordinates of the point while the grayscale value of the pixel is a representation of the Z coordinate of the point.

Point clouds

A point cloud (https://en.wikipedia.org/wiki/Point_cloud) is an unstructured set of 3D points representing discrete positions on the surface of an object.



3D point clouds are produced by various 3D scanning techniques, such as Laser Triangulation, Time of Flight or Structured Lighting.

1.2. Pixel Container Types

Reference

Images

Several image types are supported according to their pixel types: black and white, gray levels, color, etc.

[Easy.GetBestMatchingImageType](#) returns the best matching image type for a given file on disk.

BW1	1-bit black and white images (8 pixels are stored in 1 byte)	EImageBW
BW8	8-bit grayscale images (each pixel is stored in 1 byte)	EImageBW8
BW16	16-bit grayscale images (each pixel is stored in 2 bytes)	EImageBW ₁₆
BW32	32-bit grayscale images (each pixel is stored in 4 bytes)	EImageBW32
C15	15-bit color images (each pixel is stored in 2 bytes). Compatible with Microsoft® Windows RGB15 color images and MultiCam RGB15 format.	EImageC ₁₅

C16	16-bit color images (each pixel is stored in 2 bytes). Compatible with Microsoft® Windows RGB16 color images and MultiCam RGB16 format.	EImageC16
C24	C24 images store 24-bit color images (each pixel is stored in 3 bytes). Compatible with Microsoft® Windows RGB24 color images and MultiCam RGB24 format.	EImageC24
C24A	C24A images store 32-bit color images (each pixel is stored in 4 bytes). Compatible with Microsoft® Windows RGB32 color images and MultiCam RGB32 format.	EImageC24A

Depth Maps

8 and 16-bit depth map values are stored in buffers compatible with the 2D Open eVision images.

EDepth8	8-bit depth map (each pixel is stored in 1 byte as an integer)	EDepthMap8
EDepth16	16-bit depth map (each pixel is stored in 2 bytes as a fixed point)	EDepthMap16
EDepth32f	32-bit depth map (each pixel is stored in 4 bytes as a float)	EDepthMap32f

Point Clouds

Point Cloud	Set of points coordinates (stored as float)	EPointCloud
-------------	---------------------------------------------	-----------------------------

1.3. Supported Image File Types

Reference

Type	Description
BMP	Uncompressed image data format (Windows Bitmap Format)
JPEG	Lossy data compression standard issued by the Joint Photographic Expert Group registered as ISO/IEC 10918-1. Compression irretrievably loses quality.
JFIF	JPEG File Interchange Format
JPEG-2000	Data compression standard issued by the Joint Photographic Expert Group registered as ISO/IEC 15444-1 and ISO/IEC 15444-2. Open eVision supports only lossy compression format, file format and code stream variants.

Type	Description
	<ul style="list-style-type: none"> - code stream describes the image samples. - file format includes meta-information such as image resolution and color space.
PNG	Lossless data compression method (Portable Network Graphics).
Serialized	Euresys proprietary image file format obtained from the serialization of Open eVision image objects.
TIFF	<p>Tag Image File Format is currently controlled by Adobe Systems and uses the LibTIFF third-party library to process images written for 5.0 or 6.0 TIFF specification.</p> <p>File save operations are lossless and use CCITT 1D compression for 1-bit binary pixel types and LZW compression for all others.</p> <p>File load operations support all TIFF variants listed in the LibTIFF specification.</p>

1.4. Pixel and File Types Compatibility

Depth map to image conversion

For 8- and 16-bit depth maps, the `AsImage()` method returns a compatible image object (respectively `EImageBW8` and `EImageBW16`) that can be used with Open eVision's 2D processing features.

Pixel and file types compatibility

Pixel access

The recommended method to access pixels is to use `SetImagePtr` and `GetImagePtr` to embed the [image buffer](#) access in your own code. See also [Image Construction and Memory Allocation](#) and [Retrieving Pixel Values](#).

Use of the following methods should be limited because of the overhead incurred by each function call:

Direct access

`EROIBW8::GetPixel` and `SetPixel` methods are implemented in all images and ROI classes to read and write a pixel value at given coordinates. To scan all pixels of an image, you could run a double loop on the X and Y coordinates and use `GetPixel` or `SetPixel` each iteration, but this is not recommended.

**TIP**

For performance reasons, these accessors should not be used when a significant number of pixels needs to be processed. When that is the case, retrieving the internal buffer pointer using `GetBufferPtr()` and iterating on the pointer is recommended.

Quick Access to BW8 Pixels

In BW8 images, a call to `EBW8PixelAccessor::GetPixel` or `SetPixel` will be faster than a direct `EROIBW8::GetPixel` or `SetPixel`.

Supported structures

- `EBW1`, `EBW8`, `EBW32`
- `EC15 (*)`, `EC16 (*)`, `EC24 (*)`
- `EC24A`
- `EDepth8`, `EDepth16`, `EDepth32f`,

(*) These formats support RGB15 (5-5-5 bit packing), RGB16 (5-6-5 bit packing) and RGB32 (RGB + alpha channel) but they must be converted to/from EC24 using `EasyImage::Convert` before any processing.

**NOTE**

Transition with versions prior to eVision 6.5 should be seamless: image pixel types were defined using typedef of integral types, pixel values were treated as unsigned numbers and implicit conversion to/from previous types is provided.

Pixel and File Type compatibility during Load or Save operations

Type	BMP	JPEG	JPEG2000	PNG	TIFF	Serialized
BW1	Ok	N/A	N/A	Ok	Ok	Ok
BW8	Ok	Ok	Ok	Ok	Ok	Ok
BW16	N/A	N/A	Ok	Ok	Ok (***)	Ok
BW32	N/A	N/A	N/A	N/A	Ok (***)	Ok
C15	Ok	Ok (**)	Ok (**)	Ok (**)	Ok (**)	Ok
C16	Ok	Ok (**)	Ok (**)	Ok (**)	Ok (**)	Ok
C24	Ok	Ok	Ok	Ok	Ok (**)	Ok
C24A	Ok	N/A	N/A	Ok	N/A	Ok
Depth8	Ok	Ok	Ok	Ok	Ok	Ok

Type	BMP	JPEG	JPEG2000	PNG	TIFF	Serialized
Depth16	N/A	N/A	Ok	Ok	Ok (***)	Ok
Depth32f	N/A	N/A	N/A	N/A	N/A	Ok

N/A: Not supported. An exception occurs if you use the combination.

Ok: Image integrity is preserved with no data loss (apart from JPEG and JPEG2000, lossy compression).

(**) C15 and C16 formats are automatically converted into C24 during the save operation.

(***) BW16 and BW32 are not supported by Baseline TIFF readers.

1.5. Color Types

EISH: Intensity, Saturation, Hue color system.

ELAB: CIE Lightness, a*, b* color system.

ELCH: Lightness, Chroma, Hue color system.

ELSH: Lightness, Saturation, Hue color system.

ELUV: CIE Lightness, u*, v* color system.

ERGB: NTSC/PAL/SMPTE Red, Green, Blue color system.

EVSH: Value, Saturation, Hue color system.

EXYZ: CIE XYZ color system.

EYIQ: CCIR Luma, Inphase, Quadrature color system.

EYSH: CCIR Luma, Saturation, Hue color system.

EYUV: CCIR Luma, U Chroma, V Chroma color system.

2. Manipulating Pixels Containers and Files

2.1. Pixel Container File Save

Images and depth maps

The `Save` method of an image or the `SaveImage` method of a depth map or a ZMap saves the image data of an image or of a depth map or a ZMap object into a file using two arguments:

- **Path:** path, file name and file name extension.
- **Image File Type:** if omitted, the file name extension is used.

Images bigger than 65,536 (either width or height) must be saved in Open eVision proprietary format.

`Save` throws an exception when:

- The requested image file format is incompatible with the image pixel types
- The Auto file type selection method and the file name extension is not supported



TIP

When saving a 16-bit depth map, the fixed point precision is lost and the pixels are considered as 16-bit integers.

Image file type arguments

Argument	Image File Type
<code>EImageFileType_Auto(*)</code>	Automatically determined by the filename extension. See below.
<code>EImageFileType_Euresys</code>	Open eVision Serialization.
<code>EImageFileType_Bmp</code>	Windows bitmap - BMP
<code>EImageFileType_Jpeg</code>	JPEG File Interchange Format - JFIF
<code>EImageFileType_Jpeg2000</code>	JPEG 2000 File format/Code Stream -JPEG2000
<code>EImageFileType_Png</code>	Portable Network Graphics - PNG
<code>EImageFileType_Tiff</code>	Tagged Image File Format - TIFF

(*) Default value.

Assigned image file type if argument is `ImageFileType_Auto` or missing

File name extension(*)	Automatically assigned image file type
BMP	Windows Bitmap Format
JPEG, JPG	JPEG File Interchange Format - JFIF
JP2	JPEG 2000 file format
J2K, J2C	JPEG 2000 Code Stream
PNG	Portable Network Graphics
TIFF, TIF	Tagged Image File Format

(*) Case-insensitive.

Saving JPEG and JPEG2000 lossy compressions

`SaveJpeg` and `SaveJpeg2K` specify the compression quality when saving compressed images. They have two arguments:

- Path: a string of characters including the path, filename, and file name extension.
- Compression quality of the image file, an integer value in range [0: 100].
`SaveJpeg` saves image data using JPEG File Interchange Format – JFIF.
`SaveJpeg2K` saves image data using JPEG 2000 File format.

JPEG compression values

JPEG compression	Description
JPEG_DEFAULT_QUALITY (-1)	Default quality (*)
100	Superb image quality, lowest compression factor
75	Good image quality (*)
50	Normal image quality
25	Average image quality
10	Bad Image quality

(*) The default quality corresponds to the good image quality (75).

Representative JPEG 2000 compression quality values

JPEG 2000 compression	Description
-1	Default quality (*)
1	Highest image quality, lowest compression factor
16	Good Image Quality (*) (16:1 rate)
512	Lowest image quality, highest compression factor

(*) The default quality corresponds to the good image quality (16:1 rate).

Saving point clouds

Use the following methods to save a point cloud in a specific format:

- `EPointCloud::Save`: Open eVision proprietary file format.
- `EPointCloud::SaveCSV`: CSV file.
- `EPointCloud::SaveOBJ`: OBJ file.
- `EPointCloud::SavePCD`: PCD file.
- `EPointCloud::SavePLY`: PLY file.
- `EPointCloud::SaveXYZ`: XYZ file.



TIP

The PCD format is supported in ASCII and binary modes.

2.2. Pixel Container File Load

Loading images and depth maps

- Use the `Load` method to load image data into an image object:
 - It has one argument: the **path**: path, filename, and file name extension.
 - File type is determined by the file format.
 - The destination image is automatically resized according to the size of the image on disk.
- The `Load` method throws an exception when:
 - File type identification fails
 - File type is incompatible with pixel type of the image object



TIP

Serialized image files of Open eVision 1.1 and newer are incompatible with serialized image files of previous Open eVision versions.



TIP

When loading a BW16 image (with integer values) in a depth map, the fixed point precision set in the depth map (0 by default) is left unchanged and used.

Loading point clouds

Use the following methods to load a point cloud saved in a specific format:

- `EPointCloud::Load`: Open eVision proprietary file format.
- `EPointCloud::LoadCSV`: CSV file.
- `EPointCloud::LoadOBJ`: OBJ file.
- `EPointCloud::LoadPCD`: PCD file.
- `EPointCloud::LoadPLY`: PLY file.
- `EPointCloud::LoadXYZ`: XYZ file.



TIP

- The PCD format is supported in ASCII and binary modes.
- The PLY is supported only in ASCII mode.

2.3. Memory Allocation

An image can be constructed with an internal or external memory allocation.

Internal memory allocation

The image object dynamically allocates and deallocates a buffer.

- Memory management is transparent.
- When the image size changes, reallocation occurs.
- When an image object is destroyed, the buffer is deallocated.

To declare an image with internal memory allocation:

- a. Construct an image object, for instance `EImageBW8`, either with width and height arguments, OR using the `SetSize` function.
- b. Access a given pixel. There are several functions that do this. `GetImagePtr` returns a pointer to the first byte of the pixel at the given coordinates.

External memory allocation

The user controls `buffer` allocation or `links a third-party image` in the memory buffer to an Open eVision image.

- Image size and buffer address must be specified.
- When an image object is destroyed, the buffer is unaffected.

To declare an image with external memory allocation:

- a. Declare an image object, for instance `EImageBW8`.
- b. Create a suitably sized and aligned buffer (see [Image Buffer](#)).
- c. Assign the buffer to the image with `SetImagePtr`.



NOTE

If your buffer rows are not aligned on 4 bytes, you cannot use `SetImagePtr`. In that case, use `InitializeFromUnalignedBuffer` instead.

Please note, however, that this allocates the memory internally and copies the external buffer into the internal one instead of using the external one directly.

2.4. Image and Depth Map Buffer

Image and depth map pixels are stored contiguously, from left to right and from top row to bottom row, in Windows bitmap format (top-down DIB -device-independent bitmap-) into an associated buffer.

The buffer address is a pointer to the start address of the buffer, which contains the top left pixel of the image.

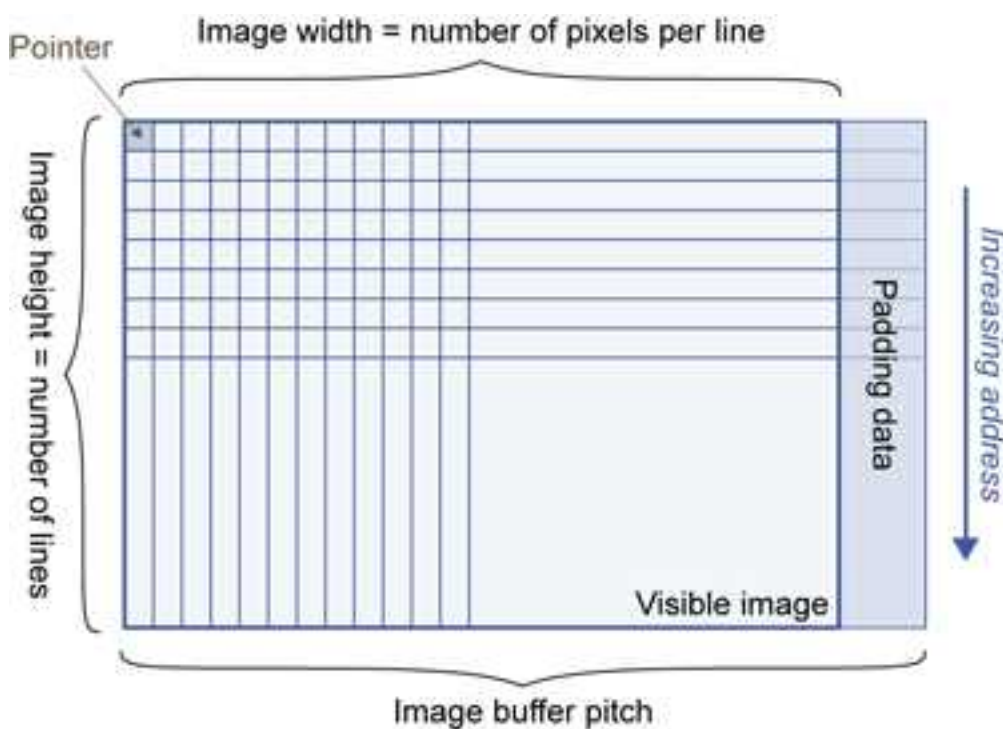


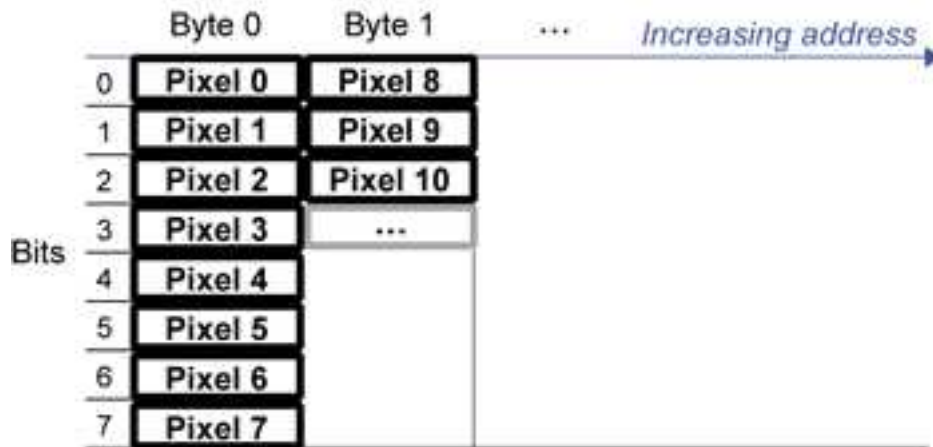
Image buffer pitch

- Alignment must be a multiple of 4 bytes.
- Open eVision 1.2 onwards default pitch is 32 bytes for performance reasons (Open eVision 1.1.5 was 8 bytes).

Memory layout

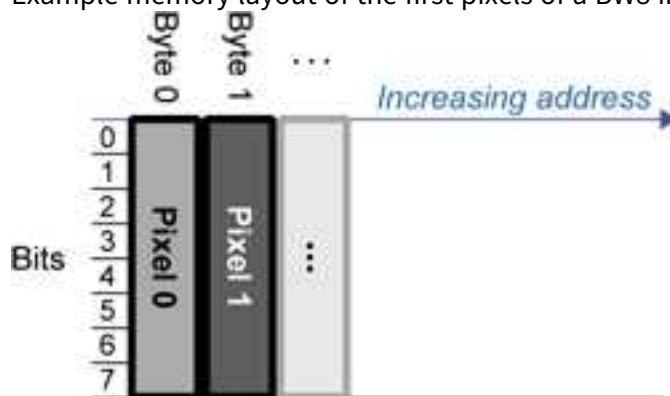
- `EImageBW` stores 8 pixels in one byte.

Example memory layout of the first 2 pixels of a BW1 image buffer:



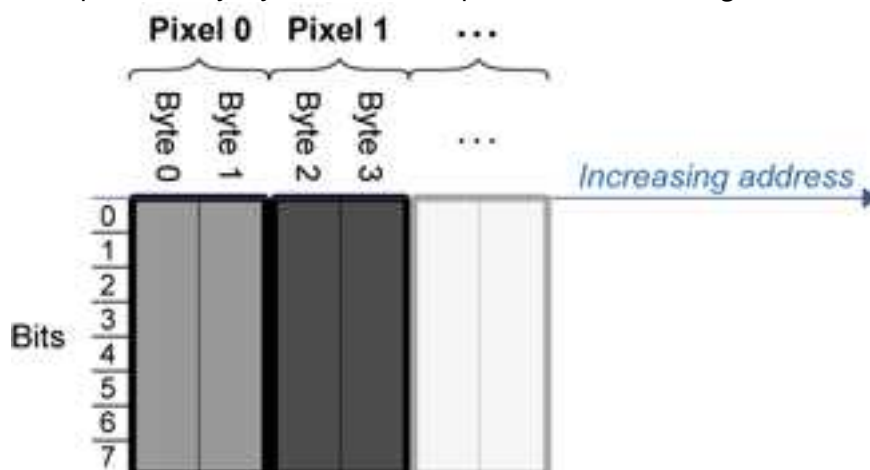
- `EImageBW8` and `EDepthMap8` store each pixel in one byte.

Example memory layout of the first pixels of a BW8 image buffer:



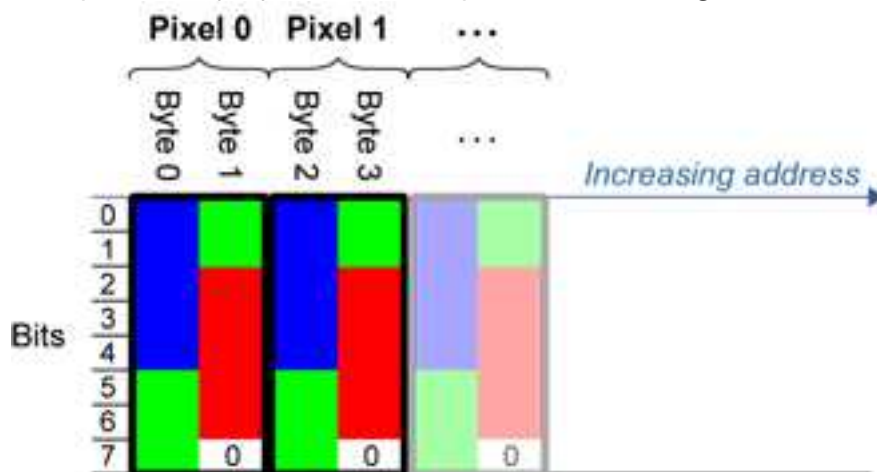
- `EImageBW-6` stores each pixel in a 16-bit word (two bytes).

Example memory layout of the first pixels of a BW16 image buffer:



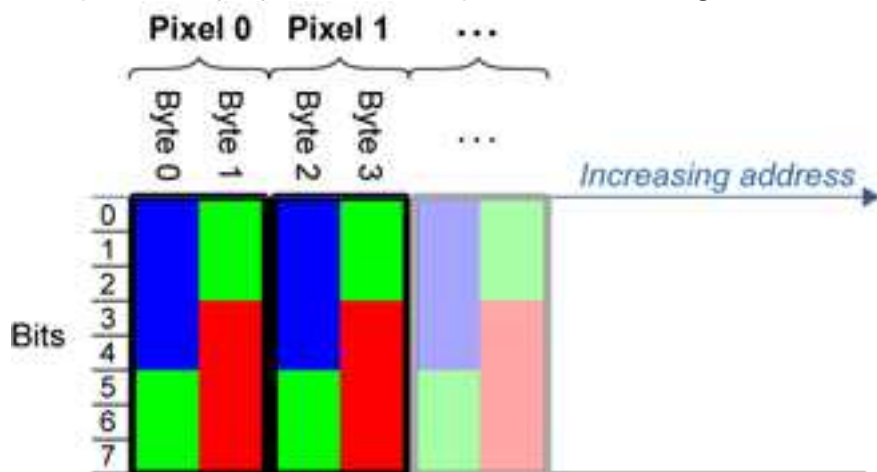
- `EImageC-5` stores each pixel in 2 bytes. Each color component is coded with 5-bits. The 16th bit is left unused.

Example memory layout of the first pixels of a C15 image buffer:



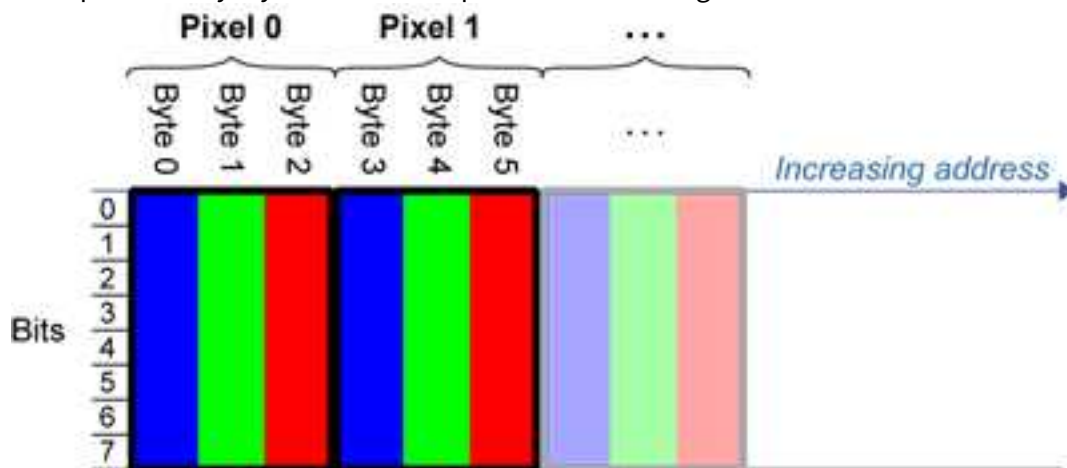
- [EImageC16](#) stores each pixel in 2 bytes. The first and third color components are coded with 5-bits. The second color component is coded with 6-bits.

Example memory layout of the first pixels of a C16 image buffer:



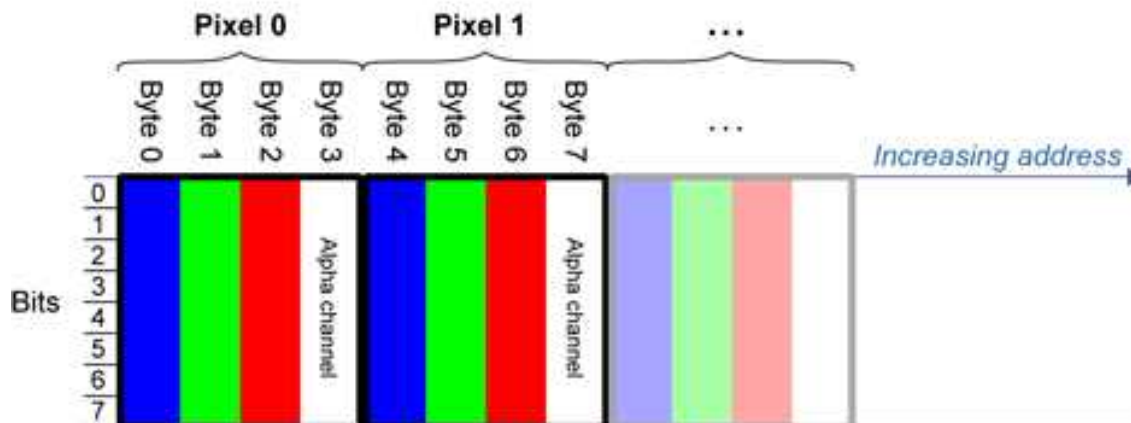
- [EDepthMap16](#) store each pixel in 2 bytes using a fixed point format.
- [EImageC24](#) stores each pixel in 3 bytes. Each color component is coded with 8-bits.

Example memory layout of the first pixels of a C24 image buffer:



- **EImageC24A** stores each pixel in 4 bytes. Each color component is coded with 8-bits. The alpha channel is also coded with 8-bits.

Example memory layout of the first pixels of a C24A image buffer:



- **EDepthMap32f** store each pixel in 4 bytes using a float format.

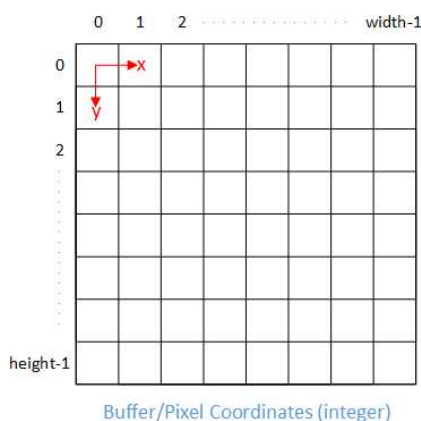
2.5. Image Coordinate Systems

The conventions below apply to all Open eVision functions and results.

- Pixel coordinates are usually given as integer numbers.
- Some results can use subpixel precision with real (floating point) numbers.
- Some exceptions apply and are documented per librarie.

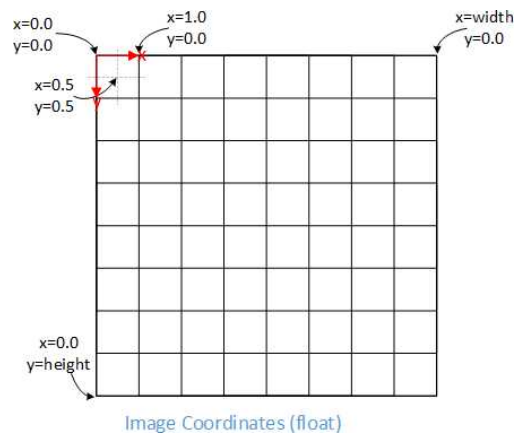
Integer coordinates

- The origin (0,0) of the coordinate system is the upper left pixel of the image.
- The lower right pixel is (width-1, height-1).



Real coordinates

- With floating point (x,y) coordinates, the origin is the upper left corner of the upper left pixel.
- The first pixel area ranges in $[0,1[$ for X and Y axis.
- Coordinates greater or equal than the width or the height are outside the image.



2.6. Image Drawing and Overlay

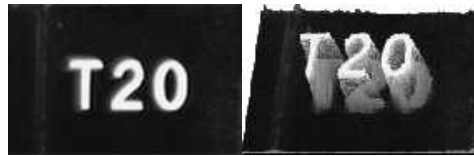
- Drawing uses Windows GDI (Graphics Device Interface) system calls.
 - MFC (Microsoft Foundation Class) applications normally use `OnDraw` event handler to draw, where a pointer to a device context is available.
 - Borland/CodeGear OWL or VCL use a `Paint` event handler.
- The color palette in 256-color display mode gives optimal rendering.
- Gray-level images can be improved using LUTs (LookUp Tables) (using histogram stretching techniques or pseudo-coloring).
- The zoom can be different horizontally and vertically.
- `DrawFrameWithCurrentPen` method draws a frame.
- *Non-destructive overlaying* drawing operations do not alter the image contents, such as `MoveTo/LineTo`.
- *Destructive overlaying* drawing operations alter the image contents by drawing inside the image such as `Easy::OpenImageGraphicContext`. Gray-level [color] images can only receive a gray-level [color] overlay.

2.7. 3D Rendering of 2D Images

These images are viewed by rotating them around the X-axis, then the Y-axis.

Gray 3D rendering

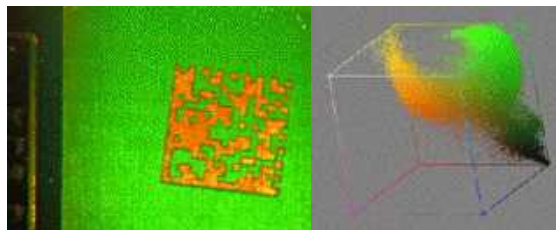
Easy: :Render3D prepares a 3-dimensional rendering where gray-level values are altitudes. Magnification factors in the three directions (X = width, Y = height and Z = depth) can be given. The rendered image appears as independent dots whose size can be adjusted to make the surface more or less opaque.



3D rendering

Color histogram 3D rendering

Easy: :RenderColorHistogram prepares a 3-dimensional rendering of a color image histogram. The pixels are drawn in the RGB space (not XY -plane) to show clustering and dispersion of RGB values. This function can process pixels in other color systems (using EasyColor to convert), but the raw RGB image is required to display the pixels in their usual colors. Magnification factors in all three directions (X = red, Y = green and Z = blue) can be given.

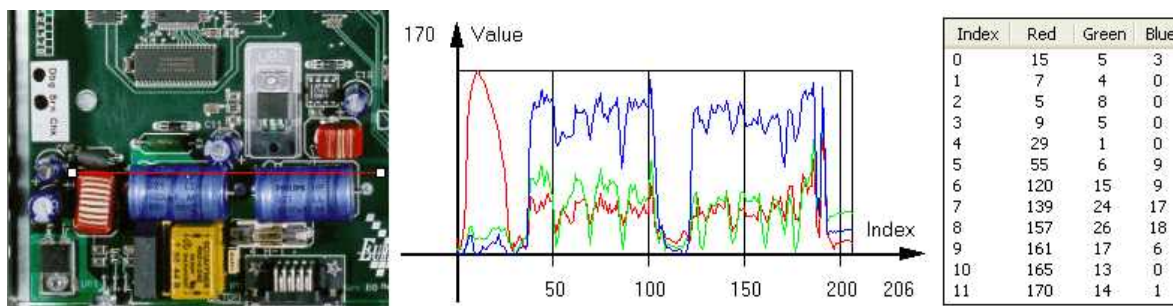


Color histogram rendering

2.8. Vector Types and Main Properties

A vector is a one-dimensional array of pixels (taken from an image [profile](#) or contour).

[EVector](#) is the base class for all vectors. It contains all non-type-specific methods, mainly for counting elements and serialization.



Profile in a C24 image, RGB values plot along profile and RGB values array ([EC24Vector](#))

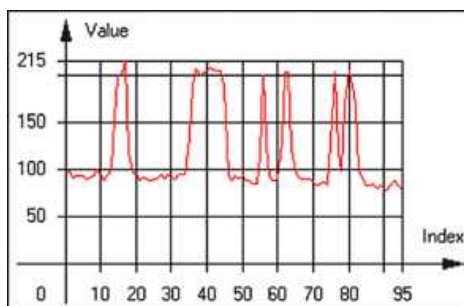
A vector manages an array of elements. Memory allocation is transparent, so vectors can be resized dynamically. Whenever a function uses a vector, the vector type, size and structure are automatically adjusted to suit the function needs.

The use of vectors is quite straightforward:

- To create a vector of the appropriate type:
 - Use its constructor and preallocate elements if required.
- To fill a vector with values:
 - Call the [EVector::Empty](#) member to empty it.
 - Call the [EC24Vector::AddElement](#) member to add elements one by one.
 - Use the indexing to access any element.
- To access a vector element, either for reading or writing:
 - Use the brackets operator [EC24Vector::operator\[\]](#).
- To determine the current number of elements:
 - Use the [EVector::NumElements](#) member.
- To draw the vector:
 - A pixel vector is a plot of the element values as a function of the element index, so its graphical appearance depends on its type. You can draw a vector in a window. For legibility, the drawing should appear on a neutral background.
 - Drawing is done in the device context associated to the desired window. By default, curves are drawn in blue and annotations in black. You can define: `graphicContext`, `width`, `height`, `originX`, `originY`, `color0`, `color1` and `color2`.
 - The [EC24Vector](#) has three curves drawn instead of one, each corresponding to a color component. By default the red, blue and green pens are used.

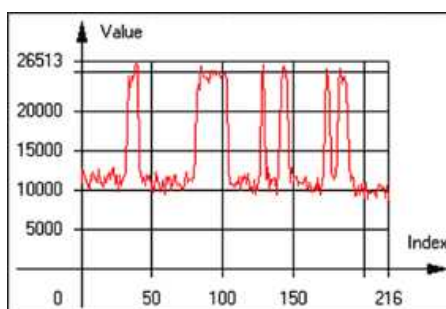
Vector types

- **EBW8Vector**: a sequence of gray-level pixel values, often extracted from an image profile (used by `EasyImage::Lut`, `EasyImage::SetupEqualize`, `EasyImage::ImageToLineSegment`, `EasyImage::LineSegmentToImage`, `EasyImage::ProfileDerivative...`).



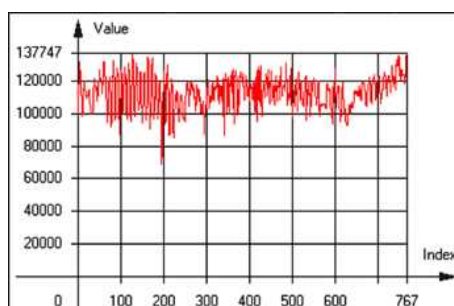
Graphical representation of an **EBW8Vector** (see [Draw](#) method)

- **EBW16Vector**: a sequence of gray-level pixel values, using an extended range (16 bits), mainly for intermediate computations.



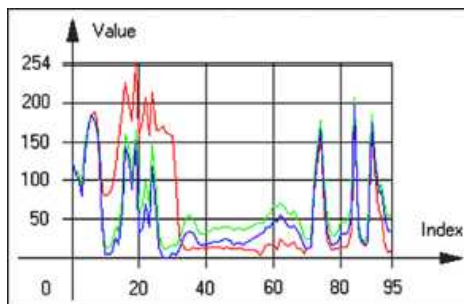
Graphical representation of an **EBW16Vector**

- **EBW32Vector**: a sequence of gray-level pixel values, using an extended range (32 bits), mainly for intermediate computations (used in `EasyImage::ProjectOnARow`, `EasyImage::ProjectOnAColumn`, ...).



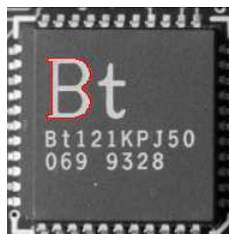
Graphical representation of an **EBW32Vector**

- **EC24Vector**: a sequence of color pixel values, often extracted from an image profile (used by `EasyImage::ImageToLineSegment`, `EasyImage::LineSegmentToImage`, `EasyImage::ProfileDerivative`, ...).



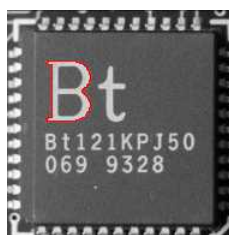
Graphical representation of an **EC24Vector**

- **EBW8PathVector**: a sequence of gray-level pixel values, extracted from an image profile or contour, with corresponding pixel coordinates (used by `EasyImage::ImageToPath`, `EasyImage::PathToImage`, ...).



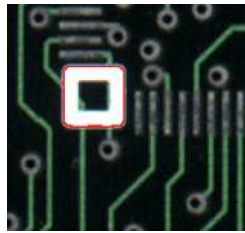
Graphical representation of an **EBW8PathVector** (see `Draw` method)

- **EBW6PathVector**: a sequence of gray-level pixel values, extracted from an image profile or contour, with corresponding pixel coordinates (used by `EasyImage::ImageToPath`, `EasyImage::PathToImage`, ...).



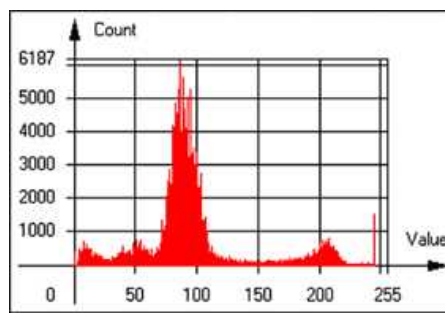
Graphical representation of an **EBW6PathVector** (see `Draw` method)

- **EC24PathVector**: a sequence of color pixel values, extracted from an image profile or contour, with corresponding pixel coordinates (used by `EasyImage::ImageToPath`, `EasyImage::PathToImage`, ...).



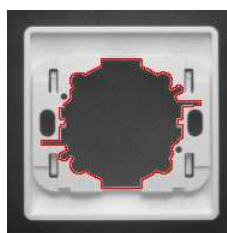
Graphical representation of an `EC24PathVector` (see `Draw` method)

- **EBWHistogramVector**: a sequence of frequency counts of pixels in a BW8 or BW16 image (used by `EasyImage::IsodataThreshold`, `EasyImage::Histogram`, `EasyImage::AnalyseHistogram`, `EasyImage::SetupEqualize`, ...).



Graphical representation of an `EBWHistogramVector` (see `Draw` method)

- **EPathVector**: a sequence of pixel coordinates. The corresponding pixels need not be contiguous (used by `EasyImage::PathToImage` and `EasyImage::Contour`).



Graphical representation of an `EPathVector` (see `Draw` method)

- **EPeakVector**: peaks found in an image profile (used by `EasyImage::GetProfilePeaks`).
- **EColorVector**: a description of colors (used by `EasyColor::ClassAverages` and `EasyColor::ClassVariances`).

2.9. ROI Main Properties

ROIs are defined by a [width](#), a [height](#), and **origin x and y coordinates**.

The origins are specified with respect to the top left corner in the parent image or ROI.

The ROI must be wholly contained in its parent image.

The processing/analysis time of a BW1 ROI is faster if [OrgX](#) and [Width](#) are multiples of 8.

Save and load

You can [save](#) or [load](#) an ROI as a separate image, to be used as if it was a full image. The ROIs perform **no memory allocation** at all and never duplicate parts of their parent image, the parent image provides them with access to its image data.

The image size of the new file must match the size of the ROI being loaded into it. The image around the ROI remains unchanged.

ROI Classes

An Open eVision ROI inherits parameters from the abstract class [EBaseROI](#).

There are several ROI types, according to their pixel type. They have the same characteristics as the corresponding [image types](#).

- [EROIBW](#)
- [EROIBW8](#)
- [EROIBW-6](#)
- [EROIBW32](#)
- [EROIC-5](#)
- [EROIC-6](#)
- [EROIC24](#)
- [EROIC24A](#)

Attachment

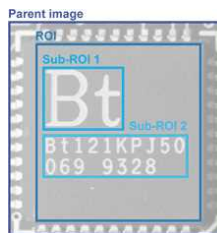
An ROI must be [attached](#) to a parent (image/ROI) with parameters that set the parent, position and size, and these links are updated transparently, avoiding dangling pointers.

A normal image cannot be attached to another image or ROI.

Nesting

Set and Get functions change or query the width, height and position of the origin of an ROI, with respect to its immediate or topmost parent image.

An image may accommodate an arbitrary number of ROIs, which can be nested in a hierarchical way. Moving the ROI also moves the embedded ROIs accordingly. The image/ROI classes provide several methods to traverse the hierarchy of ROIs associated with an image.



Nested ROIs: Two sub-ROIs attached to an ROI, itself attached to the parent image

Cropping

`CropToImage` crops an ROI which is partially out of its image. The resized ROI never grows. An exception is thrown if a function attempts to use an ROI that has limits that extend outside of the parents.



NOTE

(In Open eVision 1.0.1 and earlier, an ROI was silently resized or repositioned when placed out of its image and sometimes grew. If ROI limits extended outside parents, they were silently resized to remain within parent limits.)

Resizing and moving

ROIs can easily be resized and positioned by two functions and dragging handles:

- `EBaseROI::Drag` adjusts the ROI coordinates while the cursor moves.
- `EBaseROI::HitTest` informs if the cursor is placed over a dragging handle.
 - Once the handle is known, the cursor shape can be changed by an `OnSetCursor` MFC event handler. `HitTest` is unpredictable if called while dragging is in progress.
 - `HitTest` can be used in an `OnSetCursor` MFC event handler to change the cursor shape, or before a dragging operation like `OnLButtonDown`, (or `EvSetCursor` and `EvLButtonDown` in Borland/CodeGear's OWL) (or `FormMouseMove` and `FormMouseDown` in Borland/CodeGear's VCL).

2.10. Arbitrarily Shaped ROI (ERegion)

See also: [example: Inspecting Pads Using Regions](#) / [code snippets: ERegion](#)

Regions or arbitrarily shaped ROI

You define and use regions of interest (ROI) to restrict the area processed with your vision tool and to reduce and optimize the processing time.

In Open eVision:

- An **ROI** (`EROIxxx` class) designates a rectangular region of interest.
- A **region** (`ERegion` class) designates an arbitrarily shaped ROI. With regions, you can determine precisely which part of the image, down to a single pixel, is used for your processing.

Currently, only the following Open eVision methods support `ERegions`:

Library	Method
	<code>EasyImage::Threshold</code>
	<code>EasyImage::Copy</code>
	<code>EasyImage::ConvolveKernel</code>
	<code>EasyImage::ConvolveSymmetricKernel</code>
	<code>EasyImage::ConvolveLowpass</code>
	<code>EasyImage::ConvolveLowpass2</code>
	<code>EasyImage::ConvolveLowpass3</code>
	<code>EasyImage::ConvolveUniform</code>
	<code>EasyImage::ConvolveGaussian</code>
	<code>EasyImage::ConvolveHighpass</code>
	<code>EasyImage::ConvolveHighpass2</code>
	<code>EasyImage::ConvolveGradientX</code>
	<code>EasyImage::ConvolveGradientY</code>
	<code>EasyImage::ConvolveGradient</code>
	<code>EasyImage::ConvolveSobelX</code>
	<code>EasyImage::ConvolveSobelY</code>
	<code>EasyImage::ConvolveSobel</code>
	<code>EasyImage::ConvolvePrewittX</code>
	<code>EasyImage::ConvolvePrewittY</code>
	<code>EasyImage::ConvolvePrewitt</code>
	<code>EasyImage::ConvolveRoberts</code>
	<code>EasyImage::ConvolveLaplacianX</code>
	<code>EasyImage::ConvolveLaplacianY</code>
	<code>EasyImage::ConvolveLaplacian8</code>
	<code>EasyImage::DilateBox</code>
	<code>EasyImage::ErodeBox</code>
	<code>EasyImage::OpenBox</code>
	<code>EasyImage::CloseBox</code>
	<code>EasyImage::WhiteTopHatBox</code>
	<code>EasyImage::BlackTopHatBox</code>
	<code>EasyImage::MorphoGradientBox</code>
	<code>EasyImage::ErodeDisk</code>
EasyImage	

Library	Method
	EasyImage::DilateDisk
	EasyImage::OpenDisk
	EasyImage::CloseDisk
	EasyImage::WhiteTopHatDisk
	EasyImage::BlackTopHatDisk
	EasyImage::MorphoGradientDisk
	EasyImage::Median
	EasyImage::ScaleRotate
	EasyImage::DoubleThreshold
	EasyImage::Histogram
	EasyImage::Area
	EasyImage::AreaDoubleThreshold
	EasyImage::BinaryMoments
	EasyImage::WeightedMoments
	EasyImage::GravityCenter
	EasyImage::PixelCount
	EasyImage::PixelMax
	EasyImage::PixelMin
	EasyImage::PixelAverage
	EasyImage::PixelStat
	EasyImage::PixelVariance
	EasyImage::PixelStdDev
	EasyImage::PixelCompare
Easy3D	EDepthMapToMeshConverter::Convert
	EDepthMapToPointCloudConverter::Convert
	EStatistics::ComputePixelStatistics
	EStatistics::ComputeStatistics
	E3DObjectExtractor::Extract
	EZMapToPointCloudConverter::Convert
EasyObject	EImageEncoder::Encode
EasyFind	EPatternFinder::Find
	EPatternFinder::Learn
EasyOCR2	EOCR2::Read
	EOCR2::Detect
EasyGauge	EPointGauge::Measure
	ELineGauge::Measure
	ERectangleGauge::Measure
	ECircleGauge::Measure
	EWedgeGauge::Measure
EasyMatch	EMatcher::LearnPattern
	EMatcher::Match
EasyQRCode	EQRCodeReader::SetSearchField
	EQRCodeReader::Read



TIP

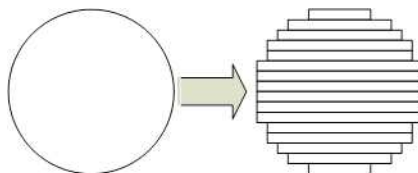
In the future Open eVision releases, the support of **ERegions** will be gradually extended to all operators.

Creating regions

Open eVision offers multiple ways to create regions, depending on the shape you need:

The [ERegion](#) is the base class for all regions and the most versatile. It encodes a region using a Run-Length Encoded (RLE) representation.

- The RLE representation of a region is made of runs (horizontal, 1-pixel high slices).
- The runs are stored in the form of their ordinate, starting abscissa and length.



Run-Length Encoding of a circle-shaped region

To create a region, either:

- Use one of the geometry-based region classes.
- Use the result of another tool, such as EasyFind, EasyMatch or EasyObject.
- Combine or modify other regions.
- Use a mask image.
- Directly provide the list of runs.

Geometry-based regions

Geometry based regions are specialized classes of regions that are encompassed in simple geometries. Open eVision currently provides classes based on a rectangle, a circle, an ellipse or a polygon.

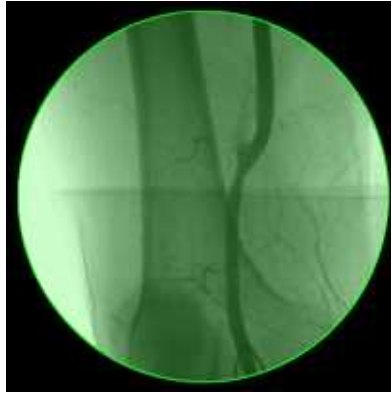
Use these classes to setup geometric regions and modify them with translation, rotation and scaling. The transformation operators return new regions, leaving the source object unchanged.

- [ERectangleRegion](#)
 - The contour of an [ERectangleRegion](#) class is a rectangle.
 - Define it using its center, width, height and angle.
 - Alternatively, use an [ERectangle](#) instance, such as one returned by an [ERectangleGauge](#) instance.



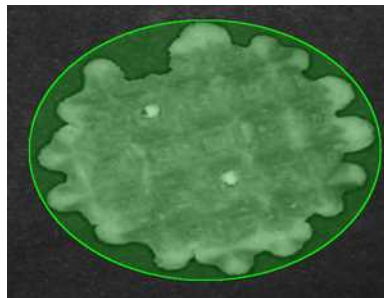
Rectangle region separating a bar code from the background

- **ECircleRegion**
 - The contour of an **ECircleRegion** class is a circle.
 - Define it using its center and radius or 3 non-aligned points.
 - Alternatively, use an **ECircle** instance, such as one returned by an **ECircleGauge** instance.



Circle region encompassing the useful part of an X-Ray image

- **EEllipseRegion**
 - The contour of an **EEllipseRegion** class is an ellipse.
 - Define it using its center, long and short radius and angle.



Ellipse region encompassing a waffle

- **EPolygonRegion**
 - The contour of an **EPolygonRegion** class is a polygon.
 - It is constructed using the list of its vertices.



Polygon region encompassing a key

Using the result of other tools

The `ERegion` class provides a set of specialized constructors to create regions from the results of another tool.

In a tool chain, these constructors restrict the processing of a tool to the area issued from the previous tool.



Open eVision provides constructors for the following tools:

- EasyFind: `EFoundPattern`
- EasyMatch: `EMatchPosition`
- EasyGauge: `ECircle` and `ERectangle`
- EasyObject: `ECodedElement`



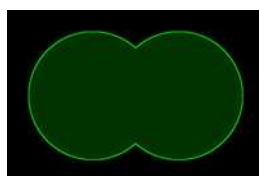
TIP

When compatible, Open eVision also provides specialized constructors for the geometry-based regions. For instance, `ECircleRegion` provides a constructor using an `ECircle`.

Combining regions

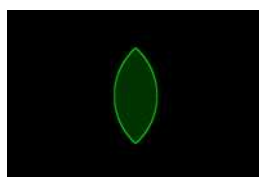
Use the following operations to create a new region by combining existing regions:

- Union
 - The `ERegion::Union(const ERegion&, const ERegion&)` method returns the region that is the addition of the two regions passed as arguments.



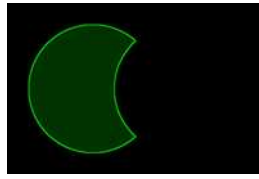
Union of 2 circles

- Intersection
 - The `ERegion::Intersection(const ERegion&, const ERegion&)` method returns the region that is the intersection of the two regions passed as argument.



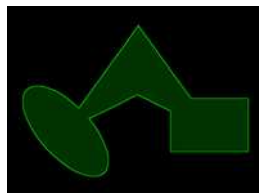
Intersection of 2 circles

- Subtraction
 - The `ERegion::Subtraction(const ERegion&, const ERegion&)` method returns the first region passed as argument after removing the second one.



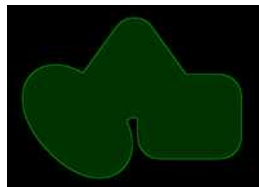
Subtraction of 2 circles

Morphological operations on regions



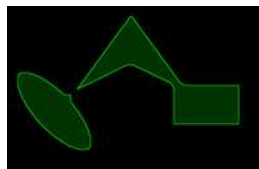
The initial arbitrary region used to illustrate the different morphological operations

- Grow
 - The `ERegion::Grow(int radius)` method returns a region that is the dilation of the region by a disk with a radius equals to the argument.



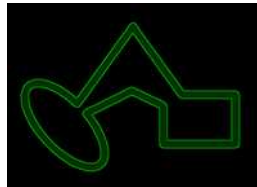
Grow of the arbitrary region

- Shrink
 - The `ERegion::Shrink(int radius)` method returns a region that is the erosion of the region by a disk with a radius equals to the argument.



Shrink of the arbitrary region

- Contour
 - The `ERegion::Contour(int thickness, bool centered = true)` method returns a region that is the contour of the region.



Contour of the arbitrary region

Free-hand drawing a region

- The `ERegionFreeHandPainter` class provides the methods that allow you to create a region by hand, using the mouse or any other user input method.
- The `RegionFreeHand` sample, available both in C++ and C#, shows how to use this class to draw a region on an image.

Using regions

The tools supporting regions provide methods that follow one of these conventions:

- `Method(const EImage& source, const ERegion& region)`
- `Method(const EImage& source, const ERegion& region, EImage& destination)`



NOTE

The source, the region and the destination must be compatible. It means that the region must at least partly fit in the source, and that source and destination must have the same size.

Preparing the region

- Open eVision automatically prepares the regions when it applies them to an image, but this preparation can take some time.
- If you do not want your first call to a method to take longer than the next ones, you can prepare the region in advance by using the appropriate `Prepare()` method.
- To manually prepare the regions, adapt the internal RLE description to your images.

Drawing regions

The `ERegion` classes provide several methods to display the regions:

- `ERegion::Draw()` draws the region area, in a semi-transparent way, in the provided device context.
- `ERegion::DrawContour()` draws the region contour in the provided device context.

- `ERegion::ToImage()` renders the region as a mask into the provided destination image.
 - You can configure the foreground and the background colors.
 - If you initialized your image with a width and a height, Open eVision renders the region inside those bounds.
 - If not, Open eVision resizes the image to contain the whole region.
 - Use `ToImage()` to create masks for the Open eVision functions that support them.

ERegions and EROIs

- The older `EROI` classes of Open eVision are compatible with the new regions.
- Some tools allow the usage of regions with source and/or destinations that are `ERoi` instead of `EImage` follow one of these conventions:
 - `Method(const ERoi& source, const ERegion& region)`
 - `Method(const ERoi& source, const ERegion& region, ERoi& destination)`



TIP

In that case, the coordinates used for the region are relative to the reduced ROI space instead of the whole image space .

ERegion and 3D

- The new regions are compatible with the 2.5D representations of Easy3D (`EDepthMap` and `EZMap`).
- You can also reduce the domain of processing when using these classes.

2.11. Flexible Masks

ROIs vs flexible masks

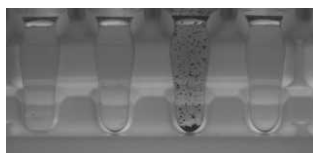
ROIs and masks restrict processing to part of an image:

- "ROI Main Properties" on page 26 apply to all Open eVision functions. Using Regions of Interest accelerates processing by reducing the number of pixels. Open eVision supports hierarchically nested rectangular ROIs.
- Flexible Masks are recommended to process disconnected ROIs or non-rectangular shapes. They are supported by some `EasyObject` and `EasyImage` library functions.

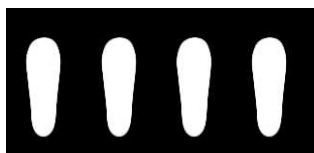
Flexible Masks

A flexible mask is a BW8 image with the same height and width as the source image. It contains shapes of areas that must be processed and ignored areas (that will not be considered during processing):

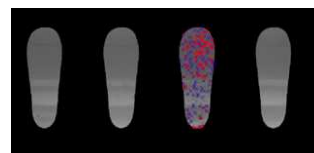
- All pixels of the flexible mask having a value of 0 define the ignored areas.
- All pixels of the flexible mask having any other value than 0 define the areas to be processed.



Source image



Associated mask

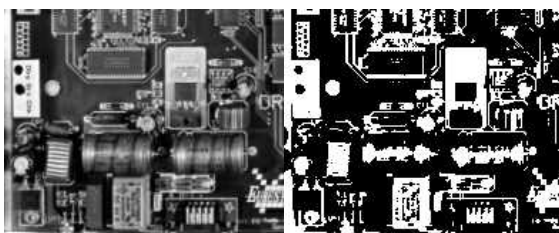


Processed masked image

A flexible mask can be generated by any application that outputs BW8 images and by some [EasyObject](#) and [EasyImage](#) functions.

Flexible Masks in EasyImage

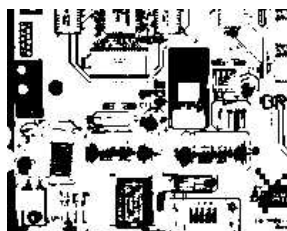
Code Snippets



Source image (left) and mask variable (right)

Simple steps to use flexible masks in Easyimage

1. Call the functions from [EasyImage](#) that take an input mask as an argument. For instance, one can evaluate the average value of the pixels in the white layer and after in the black layer.
2. Display the results.



Resulting image

EasyImage Functions that support flexible masks

- `EImageEncoder::Encode` has a flexible mask argument for BW1, BW8, BW16, and C24 source images.
- `AutoThreshold`.
- `Histogram` (function `HistogramThreshold` has no overload with mask argument).
- `RmsNoise`, `SignalNoiseRatio`.
- `Overlay` (no overload with mask argument for BW8 source images).
- `ProjectOnAColumn`, `ProjectOnARow` (Vector projection).
- `ImageToLineSegment`, `ImageToPath` (Vector profile).

Flexible Masks in EasyObject

A flexible mask can be generated by any application that outputs BW8 images or uses the Open eVision image processing functions.

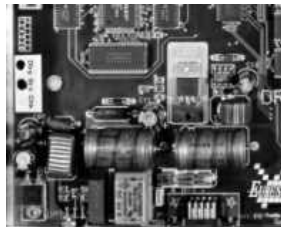
EasyObject can use flexible masks to restrict blob analysis to complex or disconnected shaped regions of the image.

If an object of interest has the same gray level as other regions of the image, you can define "keep" and "ignore" areas using flexible masks and `Encode` functions.

A flexible mask is a BW8 image with the same height and width as the source image.

- A pixel value of 0 in the flexible mask masks the corresponding source image pixel so it doesn't appear in the encoded image.
- Any other pixel value in the flexible mask causes the pixel to be encoded.

EasyObject functions that create flexible masks

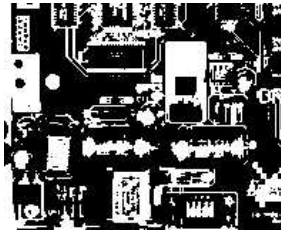


Source image

1) `ECodedImage2::RenderMask`: from a layer of an encoded image

1. To encode and extract a flexible mask, first construct a coded image from the source image.
2. Choose a segmentation method (for the image above the default method `GrayscaleSingleThreshold` is suitable).
3. Select the layer(s) of the coded image that should be encoded (i.e. white and black layers using minimum residue thresholding).
4. Make the mask image the desired size using `mask.SetSize(sourceImage.GetWidth(), sourceImage.GetHeight())`.

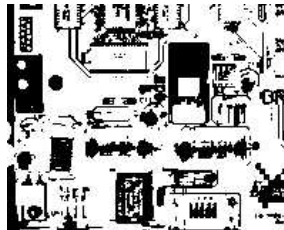
5. Exploit the flexible mask as an argument to `ECodedImage2::RenderMask`.



BW8 resulting image that can be used as a flexible mask

2) `ECodedElement::RenderMask`: from a blob or hole

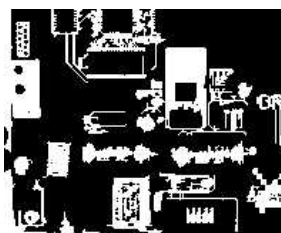
1. Select the coded elements of interest.
2. Create a loop extracting a mask from selected coded elements of the coded image using `ECodedElement::RenderMask`.
3. Optionally, compute the feature value over each of these selected coded elements.



BW8 resulting image that can be used as a flexible mask

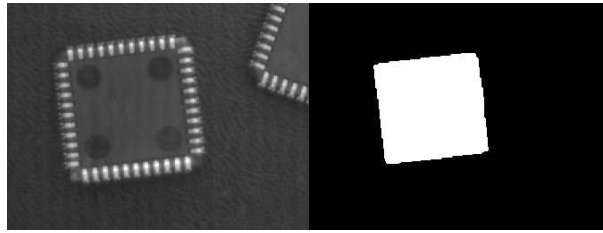
3) `EObjectSelection::RenderMask`: from a selection of blobs

`EObjectSelection::RenderMask` can, for example, discard small objects resulting from noise.



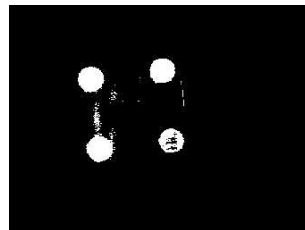
BW8 resulting image that can be used as a flexible mask

Example: Restrict the areas encoded by EasyObject



Find four circles (left) Flexible mask can isolate the central chip (right)

1. Declare a new `ECodedImage2` object.
2. Setup variables: first declare source image and flexible mask, then load them.
3. Declare an `EImageEncoder` object and, if applicable, select the appropriate segmenter. Setup the segmenter and choose the appropriate layer(s) to encode.
4. Encode the source image. Encoding a layer with just the area in the flexible mask is then pretty straightforward.
We see that the circles are correctly segmented in the black layer with the [grayscale single threshold segmenter](#):



5. Select all objects of the coded image.
6. Select objects of interest by filtering out objects that are too small.
7. Display the blob feature by iterating over the selected objects to display the chosen feature.

2.12. Profile

Code Snippets

Profile Sampling

A **profile** is a series of pixel values sampled along a line/path/contour in an image.

- `EasyImage::ImageToLineSegment` copies the pixel values along a given line segment (arbitrarily oriented and wholly contained within the image) to a vector. The vector length is adjusted automatically. This function supports flexible masks.
- A **path** is a series of [pixel coordinates](#) stored in a vector.
`EasyImage::ImageToPath` copies the corresponding pixel values to the vector. This function supports flexible masks.

- A **contour** is a closed or not (connected) path, forming the boundary of an object. `EasyImage::Contour` follows the contour of an object, and stores its constituent pixels values inside a profile vector.

Profile Analysis

The profile can be processed to find peaks or transitions:

- A transition corresponds to an object edge (black to white or white to black). It can be detected by taking the first **derivative** of the signal (which transforms transitions (edges) into peaks) and looking for peaks in it. `EasyImage::ProfileDerivative` computes the first derivative of a profile extracted from a gray-level image. The `EBW8` data type only handles unsigned values, so the derivative is shifted up by 128. Values under [above] 128 correspond to negative [positive] derivative (decreasing [increasing] slope).
- A **peak** is the portion of the signal that is above [or below] a given threshold - the maximum or minimum of the signal. This may correspond to the crossing of a white or black line or thin feature. It is defined by its:
 - **Amplitude**: difference between the threshold value and the max [or min] signal value.
 - **Area**: surface between the signal curve and the horizontal line at the given threshold.

`EasyImage::GetProfilePeaks` detects max and min peaks in a gray-level profile. To eliminate false peaks due to noise, two selection criteria are used. The result is stored in a **peaks vector**.

Profile Insertion Into an Image

`EasyImage::LineSegmentToImage` copies the pixel values from a vector or constant to the pixels of a given line segment (arbitrarily oriented and wholly contained within the image).

`EasyImage::PathToImage` copies the pixel values from a vector or a constant to the pixels of a given path.

PART I

TEXT AND CODE READING TOOLS

0.1. EasyBarCode - Reading Bar Codes

Reading Bar Codes

[Reference](#) | [Code Snippets](#)

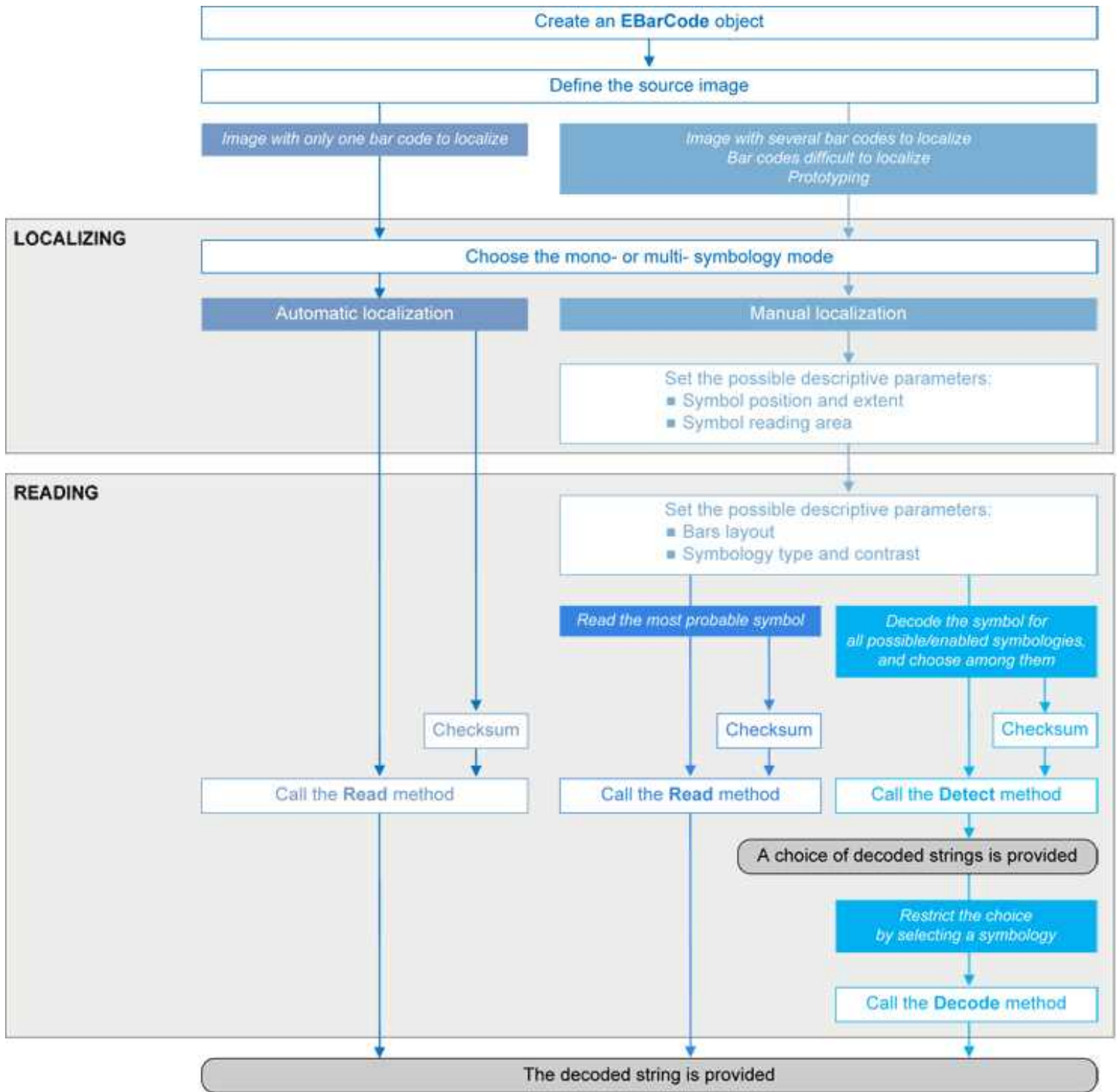


Bar code (EAN 13 symbology)

[EasyBarCode](#) can locate and read bar codes automatically.

Location can be performed manually for prototyping or when automatic mode results are unsatisfactory.

Workflow



Bar code definition

A bar code is a 2D pattern of parallel bars and spaces of varying thickness that represents a character string. It is arranged according to an encoding convention (**symbology**) that specifies the character set and encoding rules.

- The bar code may be black ink on white background or inversely white ink on black background.
- The bar code should be preceded and followed by a quiet zone of at least ten times the module width (smallest bar or space thickness).
- Bars should be surrounded below and above by a quiet zone of a few pixels.
- Bars and spaces widths must be greater than or equal to 2 pixels.

symbologies

A symbology defines the way a bar code is encoded.

Symbologies can be enabled in [StandardSymbologies](#) or [AdditionalSymbologies](#) parameters.

The standard symbologies are enabled by default:

- Code 39
- Code 128
- Code 2/5 5 Interleaved
- Codabar
- EAN 13*
- EAN 128
- MSI
- UPC A*
- UPC E



NOTE

* EAN 13 and UPC A only differ by the layout of surrounding digits.

Additional symbologies that are supported:

- ADS Anker
- Binary code
- Code 11
- Code 13
- Code 32
- Code 39 Extended (a super-set of Code 39)
- Code 39 Reduced (a subset of Code 39)
- Code 93
- Code 93 Extended
- Code 412 SEMI
- Code 2/5 3 Bars Datalogic
- Code 2/5 3 Bars Matrix
- Code 2/5 5 Bars IATA
- Code 2/5 5 Bars Industry
- Code 2/5 5 Compressed
- Code 2/5 5 Inverted

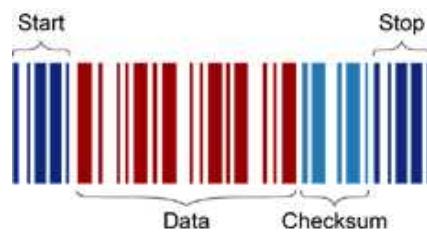
- Code BCD Matrix
- Code C.I.P
- Code STK
- EAN 8
- IBM Delta Distance A
- Plessey
- Telepen

Checksum

A checksum character enables the reader to check the barcode validity depending on the symbology:

- The checksum may be mandatory and must be checked by the reader.
- The checksum may be mandatory but may not need to be checked.
- The checksum and its verification may both be optional.

`VerifyChecksum` enables or disables (default) checksum verification.



Bar code structure (Code 39)

Read a bar code

The **Automatic** mode reading algorithm locates a bar code in the field of view and **Reads** it. If several bar codes are present, only one is located, like a straightforward hand-held bar code reader.

Before reading, the decoding symbologies must be specified in the `StandardSymbologies`, or `AdditionalSymbologies` properties.

Mono-symbology mode reads the bar code using the expected symbology type(s) and reports the encoded information (if readable) or the reason for failure (if not readable). There is only one interpretation for the character string.



Decoded bar code

Note: When the bar code contains `\0x00` characters, the `std::string::c_str` method should not be used (since C-strings are terminated by the `\0x00` character). An iterator over the characters should be used instead of a C-string.

Advanced features

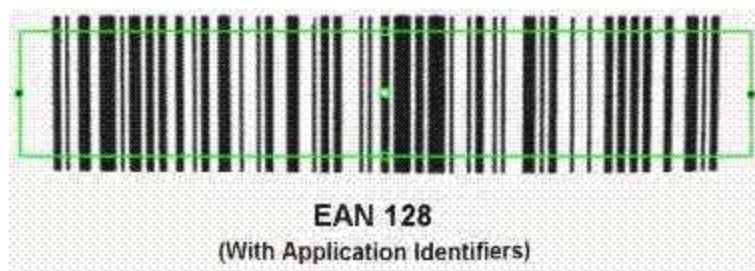
Locate and Read bar code manually

If automatic localization fails or for prototyping purposes, the user can provide the **bar code position** and **reading area** to manually locate the code.

- **Bar code position** can be provided graphically by a bounding box around the bar code or by its parameters. If several symbols appear in the image, they can be processed one after the other.
- The **reading area** of the bar code is the area that is read. It should be wider than the bar code bounding box width, and less high than the bar code bounding box height. It may also be rotated relatively to the bar code bounding box, to take into account slanting bars (Advanced mode!).



EAN 128
(With Application Identifiers)



EAN 128
(With Application Identifiers)

Bounding box — graphical appearance (manual location) Reading area — graphical appearance (manual location)

Read all interpretations (multi-symbology mode)

Use `Detect` to report the number of possible symbologies in the `NumEnabledSymbologies` property, and list the data contents by decreasing likelihood.

Then call the `Decode` method in a loop, using `GetDecodedSymbology` to walk through the list of successful symbologies in decreasing order of likelihood.

Reading Mail Bar Codes

Reference | Code Snippets

223-0057-472

Postal Code : 223-0057

Address : 472

送附期 : 2017. 7. 5日

2 2 3 - 0 0 5 7 新羽町 4 7 2



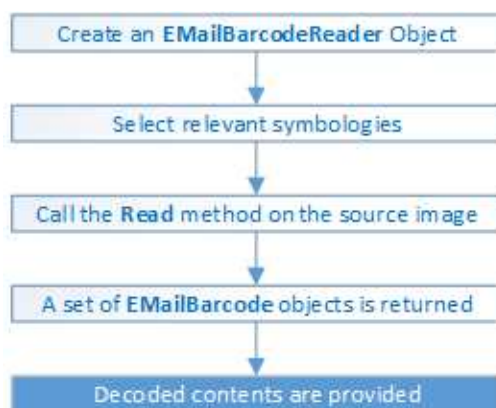
Mail bar code example

Specifications

The Mail Bar code Reader:

- Detects and decodes postal 4-state bar codes.
- Supports multiple mail bar codes in an image.
- Supports various symbologies.
- Supports the 4 main bar code orientations, with a tolerance of 3°.
- Detects bars that are at least 3 pixels wide.

Workflow



4-state bar codes

A 4-state bar code is a special kind of bar code where data is encoded on the height and position of the bars rather than their width.

Each bar can have one of 4 possible states:

- Short and centered
- Medium and elevated
- Medium and lowered
- Full height



Mail bar code symbologies

The symbology of a mail bar code specifies how to decode the bar code and how to interpret its contents.

Every country uses its own flavor of mail bar code, or symbology. Some countries, like the US, even use multiple symbologies.

As of now, the Open eVision Mail Bar code Reader supports the following symbologies:

- US: PLANET, POSTNET and Intelligent Mail
- Japan: Japan Post

Mail bar code orientation

The Open eVision Mail Bar code Reader is designed to be used in mail-handling machines. As such it is optimized to handle the 4 main orientations you encounter in such machines:

- No Rotation: The mail barcode is horizontal and read from left to right
- Rotated 90° to the right: The mail barcode is vertical and read from top to bottom
- Rotated 90° to the left: The mail barcode is vertical and read from bottom to top
- Rotated 180°: The mail barcode is upside down, horizontal, and read from right to left.

For each of these orientations, an additional rotation of -3 to 3 degrees is allowed.

Checksum

Some symbologies specify the presence of a checksum in the bar code data.

This checksum is an additional character computed from all others encoded characters. It enables the reader to check the decoded character string coherence.

- The Mail Bar code Reader allows the user to verify or not the checksum for all enabled symbologies.
- By default, checksum is not controlled.
- To enable or disable checksum verification for all enabled symbologies, set the `ValidateChecksum` property.

Reading the mail bar codes in an image

To read all the mail barcodes in a given image:

1. Create an `EMailBarcodeReader` object.
2. Optionally, select the relevant symbologies using the `ExpectedSymbologies` property.
By default, Mail Bar code Reader will consider all supported symbologies.
3. Optionally, select the relevant orientations using the `ExpectedOrientations` property.
By default, Mail Bar code Reader will test all supported orientations.
4. Call `Read` on the source image or ROI.

Each mail bar code detected is returned as an `EMailBarcode` object.

5. Each `EMailBarcode` objects contains the following information:
 - The decoded string, using the `Text` property.
 - The decoded string, split up in semantic parts, using the `ComponentStrings` property.
 - The bar code orientation, using the `Orientation` property.

- The bar code position, using the `Position` property.

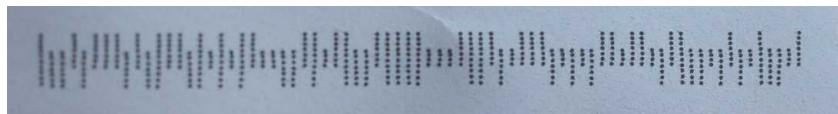


US Intelligent Mail bar code with highlighted position and decoded information

Advanced parameters

The advanced parameters of the `EMailBarcodeReader` object are:

- `EnableDottedBarcodes` activates the support for dotted barcodes (barcodes whose bars are printed with dots).
By default, this property is set to false.



Dotted Mail Barcode

- `EnableClutteredBarcodes` activates the support for cluttered barcodes (barcodes in which some bars are connected).
By default, this property is set to true.



Cluttered Mail Barcode

- `ValidateChecksum` activates the validation of the bar codes checksums, if present.
By default, this property is set to false.

0.2. EasyMatrixCode - Reading Matrix Codes

EasyMatrixCode vs EasyMatrixCode2

[Reference](#) | [Code Snippets](#)

Starting with release 2.5, Open eVision introduces a new data matrix code reading class, named [EasyMatrixCode2](#).

Compared to [EasyMatrixCode](#), it offers the following benefits:

- Ability to read multiple data matrix codes in an image.
- Support for asynchronous processing.
- Improved consistency of reading and grading results.
- Improved consistency of processing time.
- Improved handling of deformed data matrix codes.

EasyMatrixCode

Specifications

[Reference](#) | [Code Snippets](#)



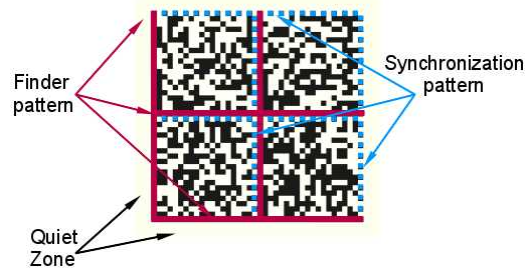
ECC 200, 26x26 cells data matrix code (left) and finder pattern (right)

In a single read operation, [EasyMatrixCode](#) locates, unscrambles, decodes, reads and grades the quality of grayscale 2D data matrix codes of any size, contrast, location and orientation (even viewed from the back on a transparent medium), providing they meet the following specifications:

- Minimum cell (= module) size: 3x3 pixels
- Maximum stretching ratio (ratio between cell width and height): 2
- Minimum quiet zone (blank zone around the matrix code) width: 3 pixels

Data Matrix Code Definition

- A data matrix code is a two-dimensional rectangular array of black and white cells which conveys a string of characters (digits, letters and special characters).
 - It is encoded to achieve maximum packing.
 - Each cell corresponds to a bit of information.
 - Additional redundant bits allow error correction for robust reading of degraded symbols.
- A data matrix code is located using the **Finder pattern**:
 - The bottom and left edges of a Data Matrix code contain only black cells.
 - The top and right edges have alternating cells.



- A data matrix code is characterized by:
 - Its **logical size** (number of cells).
 - Its **encoding type**: ECC 000 (odd symbol sizes, deprecated) or ECC 200 (even symbol sizes)..

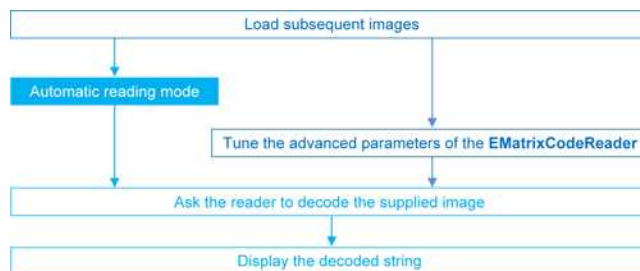


NOTE

The data matrix code definition is provided by ISO/IEC and approved as standard ISO/IEC 16022.

Workflow

[Reference](#) | [Code Snippets](#)



Reading a Matrix Code

[Reference](#) | [Code Snippets](#)

You can read the matrix code in an image automatically, using the [Read](#) method.

This method returns an [EMatrixCode](#) instance that contains the following information about the found data matrix code:

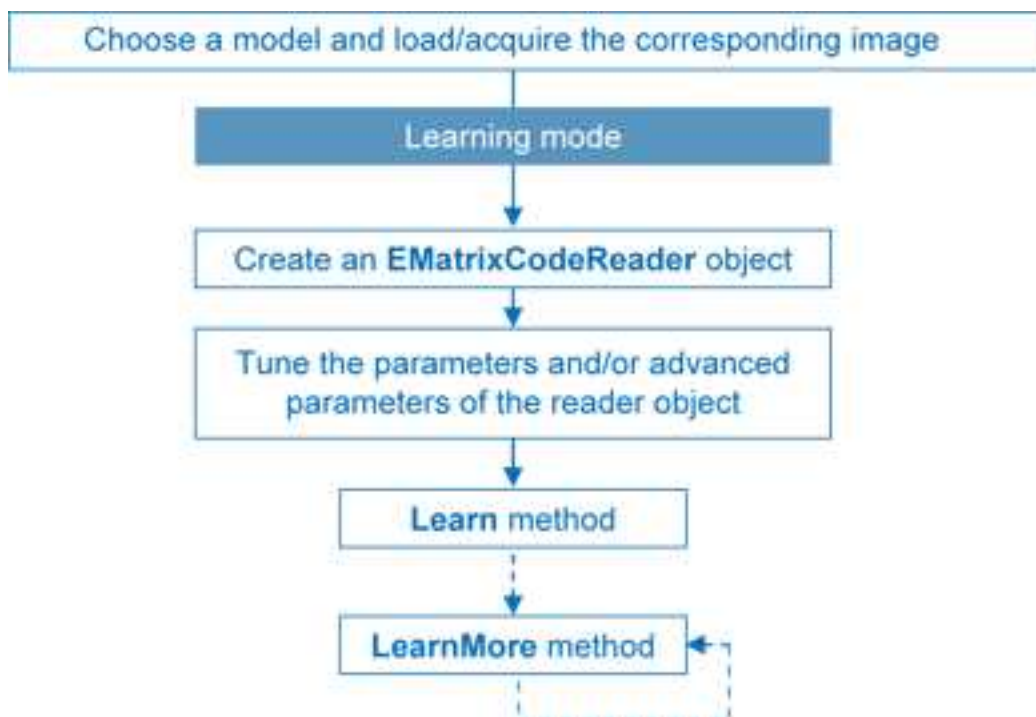
- Its decoded string,
- Its position in the image,
- Its logical size,
- Its encoding type,
- Its grading results,
- Methods to draw the data matrix code on the source image.

Learning a Matrix Code

[Reference](#) | [Code Snippets](#)

To search for specific features and speed up your processing, learn a Matrix code model.

[Workflow](#)



1. Load the image of the matrix code you want to learn.
2. Learn the model:
 - Use the [Learn](#) method with [Contrast](#), [Family](#), [Flipping](#), [Logical Size](#) parameters.
 - If you need to learn several matrix codes, use [LearnMore](#) and pass additional sample images.
 - Call [Learn](#) to replace [EMatrixCodeReader](#) parameters (calling [Learn](#) several times does not accumulate results, while [LearnMore](#) does).
3. Tune [search parameters](#) to be efficient and either:
 - Read only matrix codes that match a sample matrix code,
 - Or read only matrix codes that have the same properties ([Contrast](#), [Family](#), [Flipping](#), [Logical Size](#)) as the learned one,
 - Or disregard a search parameter of the learned matrix code [SetLearnMaskElement](#), for example to read only unflipped matrix codes. Just remove the default parameters, then add new ones.
4. Ask [EMatrixCodeReader](#) to decode the supplied image.
5. Display the [decoded string](#).
6. Save the state of the reader object using [Save](#).

Restoring the state of an EMatrixCodeReader

To restore the state of an [EMatrixCodeReader](#) and use it to read a matrix code:

1. [Load](#) an image.
2. Restore the reader state from the given file using [Load](#).
3. [Read](#) the image.
4. Display the [decoded string](#).

Computing the Print Quality

Reference | Code Snippets

To compute the print quality indicators as defined by BC11, ISO 15415, ISO/IEC TR 29158 (formerly known as AIM DPM-1-2006) and SEMI T10-0701 standards, retrieve the grades with the [GetIso545GradingParameters](#), [GetIso2958GradingParameters](#) and [GetSemiT10GradingParameters](#) accessors of the [EMatrixCode](#) class.



NOTE

The print quality of the matrix codes is computed during the [Read](#) operation, only if the [ComputeGrading](#) parameter is set to `true`.

Using GS1 Data Matrix Codes

Reference | Code Snippets

EasyMatrixCode is able to find and decode GS1-compliant data matrix codes.

The GS1 standard adds semantic identifiers to the contents of a data matrix code. These identifiers are interpreted in an easy and consistent way.

The structure of GS1-compliant content is as follows:

$$]d2 [GS1]{Id1} {Value1} [GS1]{Id2} {Value2} \dots$$

where:

- "]d2" is the string identifying a GS1-compliant stream,
- [GS1] is the GS1 escape character (0x1d),
- {Id} is an application identifier,
- {Value} is the value associated with that identifier.

Example

The string:

$$]d2 [GS1]11180112 [GS1]15190101$$

is interpreted as follows:

- It contains two GS1 parts: 11180112 and 15190101.
- The first (11180112) is composed of the identifier 11 and the value 180112, meaning that the product has a production date (the meaning of identifier 11) of January 12th, 2018.
- The second (15190101) is composed of the identifier 15 and the value 190101, meaning that the product has a best before date (the meaning of identifier 15) of January 1st, 2019.



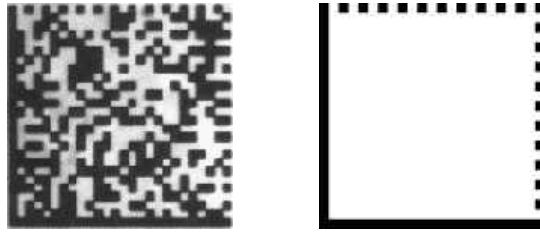
TIP

For more information, see <https://www.gs1.org/>

EasyMatrixCode2

Specifications

[Reference](#) | [Code Snippets](#)



ECC 200, 26x26 cells data matrix code (left) and finder pattern (right)

In a single read operation, [EasyMatrixCode2](#) locates, unscrambles, decodes, reads and grades the quality of grayscale 2D data matrix codes of any size, contrast, location and orientation (even viewed from the back on a transparent medium), providing they meet the following specifications:

- Minimum cell (= module) size: 3x3 pixels
- Minimum quiet zone (blank zone around the matrix code) width: 1 pixel

All the functionality of [EasyMatrixCode2](#) is available for testing in Open eVision Studio, except for the [StopProcess](#) method (for asynchronous processing).

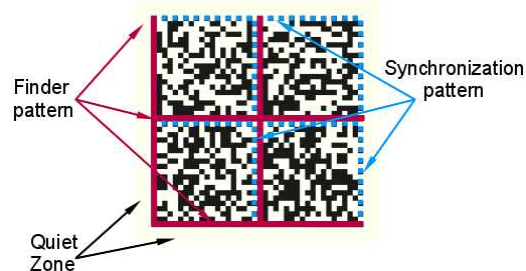


NOTE

The relevant classes of the [EasyMatrixCode2](#) library are stored in the name space “EasyMatrixCode2”.

Data Matrix Code Definition

- A data matrix code is a two-dimensional rectangular array of black and white cells which conveys a string of characters (digits, letters and special characters).
 - It is encoded to achieve maximum packing.
 - Each cell corresponds to a bit of information.
 - Additional redundant bits allow error correction for robust reading of degraded symbols.
- A data matrix code is located using the **Finder pattern**:
 - The bottom and left edges of a Data Matrix code contain only black cells.
 - The top and right edges have alternating cells.



- A data matrix code is characterized by:
 - Its **logical size** (number of cells).
 - Its **encoding type**: ECC 000 (odd symbol sizes, deprecated) or ECC 200 (even symbol sizes)..

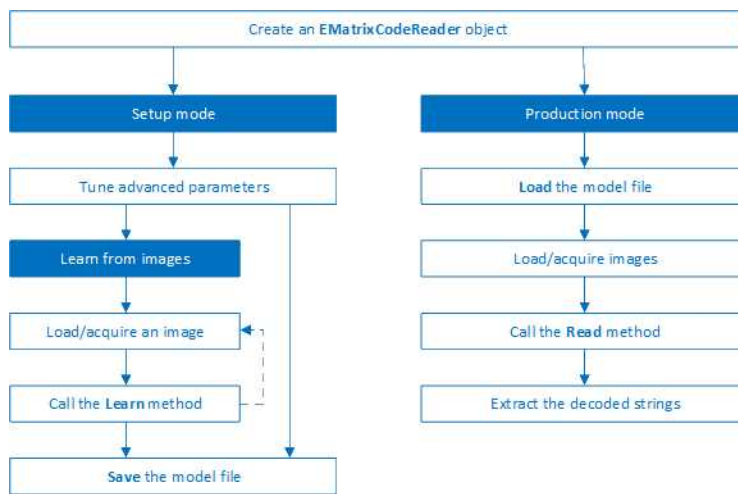


NOTE

The data matrix code definition is provided by ISO/IEC and approved as standard ISO/IEC 16022.

Workflow

[Reference](#) | [Code Snippets](#)



1. Load the image.
2. Read the data matrix codes in the image using `EMatrixCodeReader.Read()`.
3. Loop on found data matrix codes.
4. Display the decoded text.

Reading a Matrix Code

[Reference](#) | [Code Snippets](#) | dedicated code snippet: [Reading Matrix Codes from an Image](#)

You can read the matrix code in an image automatically as follows:

- a. Create an `EMatrixCodeReader` object.
- b. Call the `Read` method to detect and decode the matrix codes in the image.
- c. Call the `GetReadResults` accessor to retrieve the decoded `EMatrixCode` instances.

The `EMatrixCode` instances contain the following information for each found data matrix code:

- Its decoded string,
- Its position in the image,
- Its logical size,
- Its encoding type,
- Its grading results,
- Methods to draw the data matrix code on the source image.

Learning a Matrix Code

[Reference](#) | [Code Snippets](#) | dedicated code snippet: [Reading with Prior Learning](#)

To improve the processing times of the `Read` method, learn a matrix code model from representative images as follows:

1. Load the image of the matrix code you want to learn from.
2. Call the `Learn` method to learn from the image.
3. Repeat with additional images if necessary.
4. Save the `EMatrixCodeReader` state to the disk with the `Save` method.

The `Learn` method re-orders the internal processing structure used to detect and decode the matrix codes in such a way that the learned codes are found faster.



TIP

The user-defined advanced parameters (`MaxNumCodes`, `Timeout`, `ReadMode` and `ComputeGrading`) are not affected by the `Learn` method .

If the `Learn` method is not able to detect any code in the image, it throws an exception.



TIP

The internal processing structure is not affected in this situation.

Restoring the state of an `EMatrixCodeReader`

- To restore a previously saved `EMatrixCodeReader` state , call the `Load` method.
- To restore the default state of an `EMatrixCodeReader` instance, call the `ResetLearning` method.

Computing the Print Quality

[Reference](#) | [Code Snippets](#) | dedicated code snippet: [Inspecting Print Quality Grades](#)

To compute the print quality indicators as defined by BC11, ISO 15415, ISO/IEC TR 29158 (formerly known as AIM DPM-1-2006) and SEMI T10-0701 standards, retrieve the grades with the [GetIso545GradingParameters](#), [GetIso2958GradingParameters](#) and [GetSemiT10GradingParameters](#) accessors of the [EMatrixCode](#) class.



NOTE

The print quality of the matrix codes is computed during the [Read](#) operation, only if the [ComputeGrading](#) parameter is set to `true`.

Using GS1 Data Matrix Codes

[Reference](#) | [Code Snippets](#)

`EasyMatrixCode2` is able to find and decode GS1-compliant data matrix codes.

The GS1 standard adds semantic identifiers to the contents of a data matrix code. These identifiers are interpreted in an easy and consistent way.

The structure of GS1-compliant content is as follows:

$$]d2 [GS1] \{Id1\} \{Value1\} [GS1] \{Id2\} \{Value2\} \dots$$

where:

- “[d2” is the string identifying a GS1-compliant stream,
- [GS1] is the GS1 escape character (0x1d),
- {Id} is an application identifier,
- {Value} is the value associated with that identifier.

Example

The string:

$$]d2 [GS1] 11180112 [GS1] 15190101$$

is interpreted as follows:

- It contains two GS1 parts: 11180112 and 15190101.
- The first (11180112) is composed of the identifier 11 and the value 180112, meaning that the product has a production date (the meaning of identifier 11) of January 12th, 2018.
- The second (15190101) is composed of the identifier 15 and the value 190101, meaning that the product has a best before date (the meaning of identifier 15) of January 1st, 2019.



TIP

For more information, see <https://www.gs1.org/>

Asynchronous Processing

[Reference](#) | [Code Snippets](#)

EasyMatrixCode2 supports asynchronous processing. This means that you can launch multiple processing threads in parallel, each reading the matrix codes in its own image.

From the main thread, to manually stop the [Read](#) method in any of these processing threads at any time, use the [StopProcess](#) method.

When you manually stop the [Read](#) method:

- The search for matrix codes stops immediately, whether it has found matrix codes in the image or not.
- To retrieve all matrix codes found before the manual stop, use the [GetReadResults](#) accessor.

Advanced Parameters

[Reference](#) | [Code Snippets](#)

Tune the following parameters to optimize the performance of EasyMatrixCode2.

- The [MaxNumCodes](#) parameter:
 - Tells the [EMatrixCode2Reader](#) the number of codes that can be in the image.
 - Affects the computational time of the [Read](#) method.
 - Is set to 1 by default. This means that the [EMatrixCodeReader](#) only detects a single matrix code per image.
 - If set to 0, it tells the [EMatrixCodeReader](#) to find as many codes as possible in the image.
- The [Timeout](#) parameter:
 - Limits the amount of time that the [Read](#) and [Learn](#) methods may take to process a single image.
 - Is defined in microseconds.
 - Is set, by default, to a value that exceeds one hour.
- The [ReadMode](#) parameter affects the behavior of the [Read](#) method:
 - The setting [EReadMode_Speed](#) results in the shortest processing times and the [Read](#) method stops as soon as one of the following is true:
 - The method has found [MaxNumCodes](#) codes.
 - The method reaches the [Timeout](#) time limit.
 - The [Read](#) process is completely finished.
 - The setting [EReadMode_Quality](#) results in the best grading results and the [Read](#) method keeps trying to improve its detection until one of the following is true:
 - The method reaches the [Timeout](#) time limit.
 - The [Read](#) process is completely finished.
- The [ComputeGrading](#) parameter:
 - Determines if the [Read](#) method computes the grading properties of the [EMatrixCode](#) object.
 - Is set to `False` by default.

After the tuning:

- Use the [Save](#) method to store the state of the [EMatrixCodeReader](#) on the disk.
- Use the [Load](#) method, at any time, to restore the saved state.



TIP

The [Save](#) and [Load](#) methods also store the effects of [Learning](#).

0.3. EasyQRCode - Reading QR Codes

Workflow

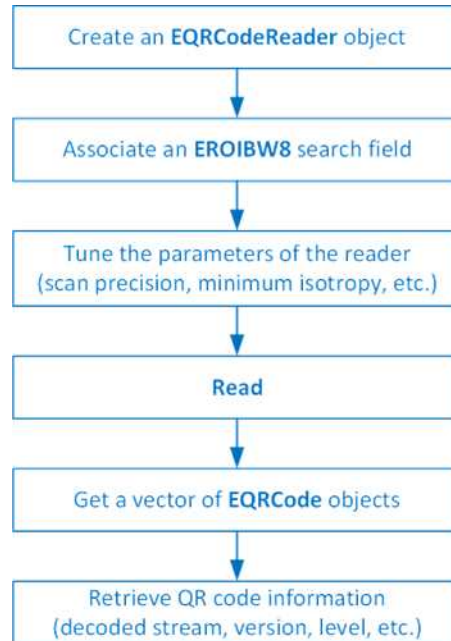
[EasyQRCode](#)



[EasyQRCode](#) detects QR (Quick Response) codes in an image, decodes them, and returns their data.

Error detection and correction algorithms ensure that poorly-printed or distorted QR codes can still be read correctly.

Workflow



QR Codes Specifications

QR code definition

A QR code is a square array of dark and light dots. One dot (or "*module*") represents one bit of information.

QR codes contain various types of data and can be different models, versions, and levels. They always contain a message, metadata about alignment, size, format, and error correction bits. They comply with the international standard ISO/IEC 18004 (1, 2 and 2005).

QR code structure

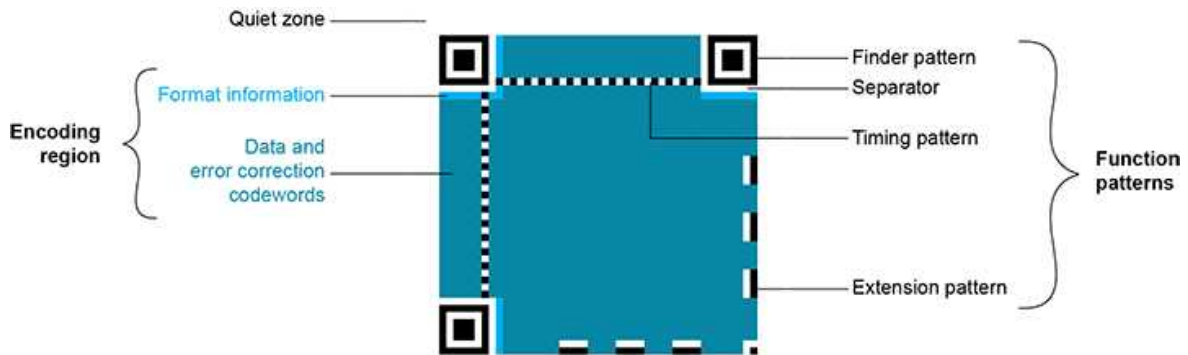
The QR code symbol consists of an *encoding region*, containing data and error correction codewords, and of *function patterns*, containing symbol metadata and position data.

A QR code must be structured with the following elements:

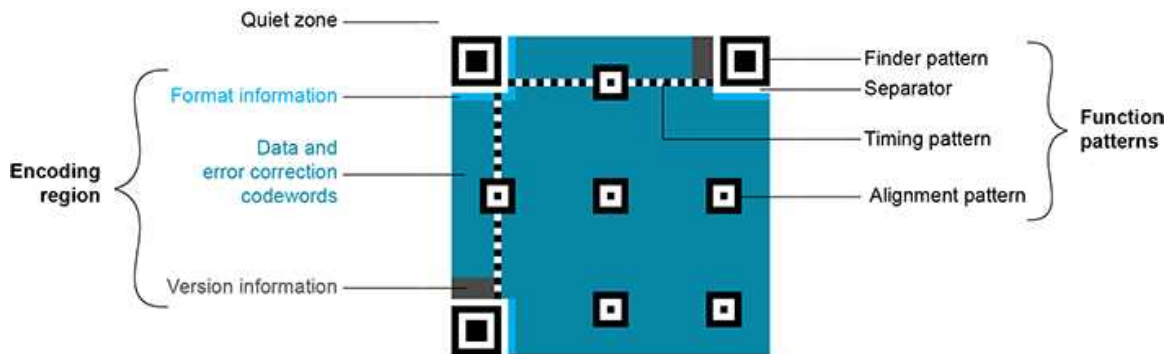
- *Quiet zone*: blank margin around the QR code
- *Finder patterns*: recognizable zones identifying a QR code
- *Extension patterns*: markers for the alignment of the QR code (model 1)
- *Alignment patterns*: markers for the alignment of the QR code (models 2 and 2005)
- *Timing Patterns*: data giving the module size (in pixels)
- *Format information*: zones providing the QR code level
- *Version information*: data giving the QR code size, for instance 25 x 25 modules (models 2 and 2005)

- *Data contents and error correction codewords*: the primary information carried by the symbol, with additional information for error correction

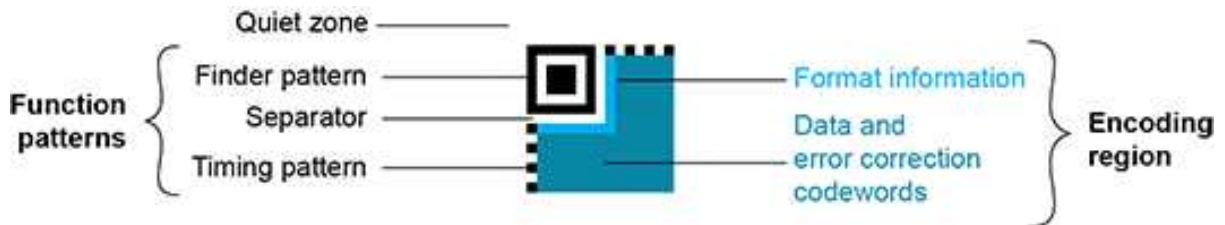
Variants of this structure exist, according to the model, format, or version of the QR code. For instance, model 1 QR codes do not feature alignment patterns but extension patterns. Micro QR codes include only one finder pattern, and no alignment pattern.



Structure of a model 1 QR code symbol



Structure of a QR code 2005 symbol



Structure of a Micro QR code symbol

QR code subtypes

A QR code can be one of the following subtypes:

- *Basic*: the default subtype.
- *ECI* (Extended Channel Interpretation): the ECI subtype provides a consistent method to embed interpretation information of data in the QR code. The ECI protocol is defined in the AIM Inc. International Technical Specification. (ECI is not available for Micro QR code symbols.)
- *GS1*: the data contained in the QR code are formatted in accordance with the GS1 General Specification.
- *AIM*: the data contained in the QR code are formatted in accordance with a specific industry application previously agreed with AIM Inc. The application indicator value is embedded in the QR code data.

Data types

The QR code data can be any mix of these types:

- *Numeric data* (0-9)
- *Alphanumeric data* (0-9, A-Z, /, \$, %...)
- *Byte data* (possibly ECI-encoded)
- *Kanji characters*

Byte data interpretation

In a QR code, the byte data can represent any information. Their interpretation depends on the subtype of the QR code:

- Basic subtype:
 - If some byte data are present in the QR code, you need to know how to interpret them.
 - Use the `EByteInterpretationMode` enum to select the corresponding byte interpretation mode (see the retrieving decoded data section in "[Reading QR Codes](#)" on page 64 for more details).
- ECI-encoded byte data:
 - The ECI subtype provides an ECI table indicator.
 - This indicator defines the character set to use to interpret the byte data.
 - EasyQRCode currently supports the UTF8 conversion table (ECI table indicator 26).

Models (Standards)

- *Model 1*: original QR code international standard, with versions ranging from 1 to 14. Note that the "version" of a QR code is the symbol size (in number of modules). It does not relate to the version of the standard, which is called the "model".
- *Model 2*: improvement of model 1. It provides versions from 1 to 40. It defines alignment patterns to improve reading of distorted QR codes, or QR codes printed on curved surfaces.
- *Model 2005*: improvement of model 2, including white-on-black QR codes, and mirror symbol orientation.
- *Micro QR codes*: smaller QR codes, from version *M1* to version *M4*. They have been introduced to save printing space.

Versions (Symbol Size)

- *QR codes*: from version 1 (21 x 21 modules) to version 40 (177 x 177 modules), with an increment of +4 x +4 modules (version 2: 25 x 25 modules, version 3: 29 x 29 modules, ..., version 39: 173 x 173 modules).
- *Micro QR codes*: version M1 (11 x 11 modules), version M2 (13 x 13 modules), version M3 (15 x 15 modules), version M4 (17 x 17 modules).



Examples of QR codes

From left to right:

Micro QR code, version M3, 15 x 15 modules,
Model 2 QR code, version 4, 33 x 33 modules, 67-114 characters,
Model 2 QR code, version 40, 177 x 177 modules, 1852-4296 characters

Levels (Error Correction)

QR codes contain error correction data. The standard offers the following levels of error correction:

- *L*: (low) about 7% of codewords can be restored
- *M*: (medium) 15%
- *Q*: (quality) 25%
- *H*: (high) 30% (not available for Micro QR codes)

For Micro QR code symbols, the available error correction levels depend on the version:

- M1 has only error detection
- M2 and M3 support L and M levels
- M4 supports L, M and Q levels

QR code geometry

When the QR code reader finds an array of dots that could match a QR code, it returns the "geometry" of this QR code candidate.

A [QR code geometry](#) is a set of points:

- It contains the coordinates of the [corners](#) of the QR code [quadrangle](#) (bottom left, top left, top right, bottom right).
- It contains the coordinates of the [finder pattern centers](#) (bottom left, top left, top right).
- For a Micro QR code symbol, the coordinates for a single [finder pattern center](#) (link) are returned.

EasyQRCode uses a float coordinate system and the origin (0.0, 0.0) is the top left corner of the top left pixel of the image.



QR code geometry

Read a QR code

Reading a QR code returns information about every QR codes found in the given search field (see ["Reading QR Codes" on page 64](#)).

Reading QR Codes

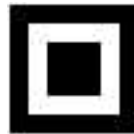
Read a QR code

1. Set a [search field](#) on an [EROIBW8](#) image.
2. If needed, tune the parameters to restrict the number of operations to process.
3. The QR code reader scans the image and searches for 3 finder patterns that could match a QR code, with the following requirements:
 - Minimum quiet zone (blank zone around the QR code) width: 3 pixels.
 - Minimum module size: 3 x 3 pixels.

- Minimum isotropy: 0.5.
 - Maximum corner deformation: 15° (corner angles can range from 75° to 105°).
4. The QR code reader uses the **gravity center** of the **QR code geometries** to sort the QR code candidates in line then columns order starting from the top left corner of the image.
 5. The QR code reader decodes the QR candidates and returns the **QR code: model, version, level, geometry** and the **decoded data** as described below.
 6. The reader can report the amount of **unused error correction**.
 - Close to 1, very few errors were corrected when decoding the data. The decoding is highly reliable, and the QR code is of good quality.
 - Close to 0, many errors were corrected when decoding the data. The decoding is reliable, but the QR code quality is poor.
 - -1, error correction failed. Decoding was not performed.

Tune the search parameters

- **Scan precision:** You can change the scan precision to scan the search field with:
 - A fine precision (recommended for small QR codes)
 - A coarse precision (recommended for medium to large QR codes)
- **Minimum score:** The QR code reader searches for this QR code finder pattern:



- A perfect match returns a pattern finder score of 1.
 - Less accurate matches return lower scores.
 - The minimum score allowed by default is 0.65 - you can tune this.
- **Minimum isotropy:** The isotropy of a QR code represents its rectangular deformation.
 - Perfectly square QR codes have an isotropy of 1 (short side divided by long side, whether the rectangle is vertical or horizontal).
 - EasyQRCode can detect rectangle QR codes with an isotropy down to 0.5.
 - The default **minimum isotropy** is 0.8, it can be tuned from 0 to 1.



Square and rectangular QR codes (isotropy = 1, 0.5, and 0.5 from left to right)

- **Model** and **Version:** By default, the QR code reader searches for QR codes of model 1 and 2, and all versions.

- You can shorten the process by specifying the QR code **model(s)** and a range of **versions** (from 1 (**minimum**) to 40 (**maximum**)) to search for.
- By default, the QR code reader does not search for Micro QR code symbols.

Retrieve the decoded data

Retrieving methods

To retrieve the decoded data, you can (in growing complexity order):

1. Use the `GetDecodedString` method of an `EQRCode` object.
 - This method returns an UTF-8 formatted string that contains the concatenated data of the QR code.
 - It can take an `EByteInterpretationMode` as argument.
2. Use the `GetDecodedString` method of the `EQRCodeDecodedStreamPart` objects.
 - This method is called on a part and returns an UTF-8 formatted string that contains the data of this part.
 - It can take an `EByteInterpretationMode` as argument.
 - Concatenate the decoded string of each part.
3. Use the `GetDecodedData` method of the `EQRCodeDecodedStreamPart` objects.
 - This method is called on a part and returns a vector of bytes that contains the data of this part.
 - Interpret the data according to the **coding mode** of the QR code and the **encoding** of each part.
 - Concatenate the interpreted data of each part.

Interpreting the encoded data

The QR code data can be encoded in either alphanumeric, numeric or byte modes. If a QR code contains bytes, the interpretation mode of these bytes can be embedded in the QR code through the ECI protocol or you must specify or know it.

Use the dedicated `EByteInterpretationMode` for this purpose:

- `EByteInterpretationMode_Hexadecimal`
 - Converts all bytes to their hexadecimal values (2 characters per byte).
 - The escape character `0xEFBFBD` surrounds the converted byte parts.
 - This mode overrides the ECI table indicator if it is present.
- `EByteInterpretationMode_UTF8`
 - Converts all bytes to UTF-8 if possible.
 - The `GetDecodedString` method throws an `EException` if the data are not UTF-8 compatible.
- `EByteInterpretationMode_Auto`
 - Converts all bytes in the best possible way following the ECI protocol.

The `decoded string` returns the concatenated data of the QR code in UTF-8 format:

- If bytes are present in the QR code data without ECI, specify the `byte interpretation mode` when you call the `GetDecodedString` method.
- If bytes are present in the QR code data with ECI encoding, use the corresponding byte interpretation table (currently, only table ECI 26: UTF-8 is available).
- The `hexadecimal byte interpretation mode` does not throw an exception and returns all bytes parts present in the data in their hexadecimal form (2 characters per byte) surrounded by the `0xEFBBBF` escape character.
- See the code snippet "[Retrieving Information of a QR Code](#)" on page 112.

The `decoded stream` class consists of:

- A coding mode (`basic`, `ECI`, `FNC1/GS` or `FNC1/AIM`).
- An application indicator (if the coding mode is `FNC1/AIM`, otherwise 0).

The `decoded data`:

- Is accessible from each part of the decoded stream.
- Is interpreted according to its encoding (numeric, alphanumeric, byte or Kanji) and the `ECI table indicator` (if the coding mode is `ECI`, otherwise `-1`).
- Can be the raw bit stream (the bit data after unmasking and error correction, but before decoding as a vector of bytes).
- Can be the corresponding `decoded string` (specify a `byte interpretation mode` if the encoding is byte without ECI coding mode or if the ECI table is not supported).
- See also the code snippet [Retrieving the Decoded Data \(Advanced\)](#).

Computing the print quality

- The print quality indicators as defined by ISO 15415 and ISO/IEC TR 29158 (formerly known as AIM DPM-1-2006) are computed during the `Read` operation, but only if `QRCodeReader::ComputeGrading` is set to `TRUE`.
 - The print quality is not yet supported for Micro QR code models.
- Use the `QRCode::GetIso15415GradingParameters` and `QRCode::GetIso29158GradingParameters` methods to retrieve the grades.
- Using the grading:
 - For more accurate results, it requires modules to be at least 10 pixels in width.
 - It requires a 1-module quiet zone for grading.
 - It evaluates the `Fixed Pattern Damage` with a 4-module quiet zone around the finder patterns. If this condition is not met, the `Fixed Pattern Parameter Grade` is returned as `-1`. This result affects the overall symbol grade.
 - The `Version Additional Parameter` is returned as `-1` when it is not applicable. In this case, this result is ignored in the overall symbol grade.
 - The implementation follows closely the standard but the grades also depend on the decoding algorithm. So the results may slightly differ according to the Open eVision version.
- The print quality computation is not yet available for Micro QR codes.

Multithreading

The `Read` method supports multithreading.

- Multithreading splits the load between the detection methods (such as `AdaptiveThreshold` and `Gradient`) and decodes multiple candidates in parallel. This is useful when there are several codes in the image.

0.4. EasyOCR - Reading Texts

Workflow

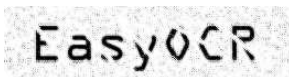
[Reference](#) | [Code Snippets](#)

EasyOCR

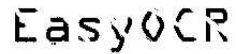
EasyOCR optical character recognition library reads short texts (such as serial numbers, part numbers and dates).

It uses font files (pre-defined OCR-A, OCR-B and Semi standard fonts, or other learned fonts) with a template matching algorithm that can recognize even badly printed, broken or connected characters of any size.

There are 4 steps to recognizing characters:



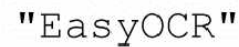
1. Raw image



2. Object segmentation

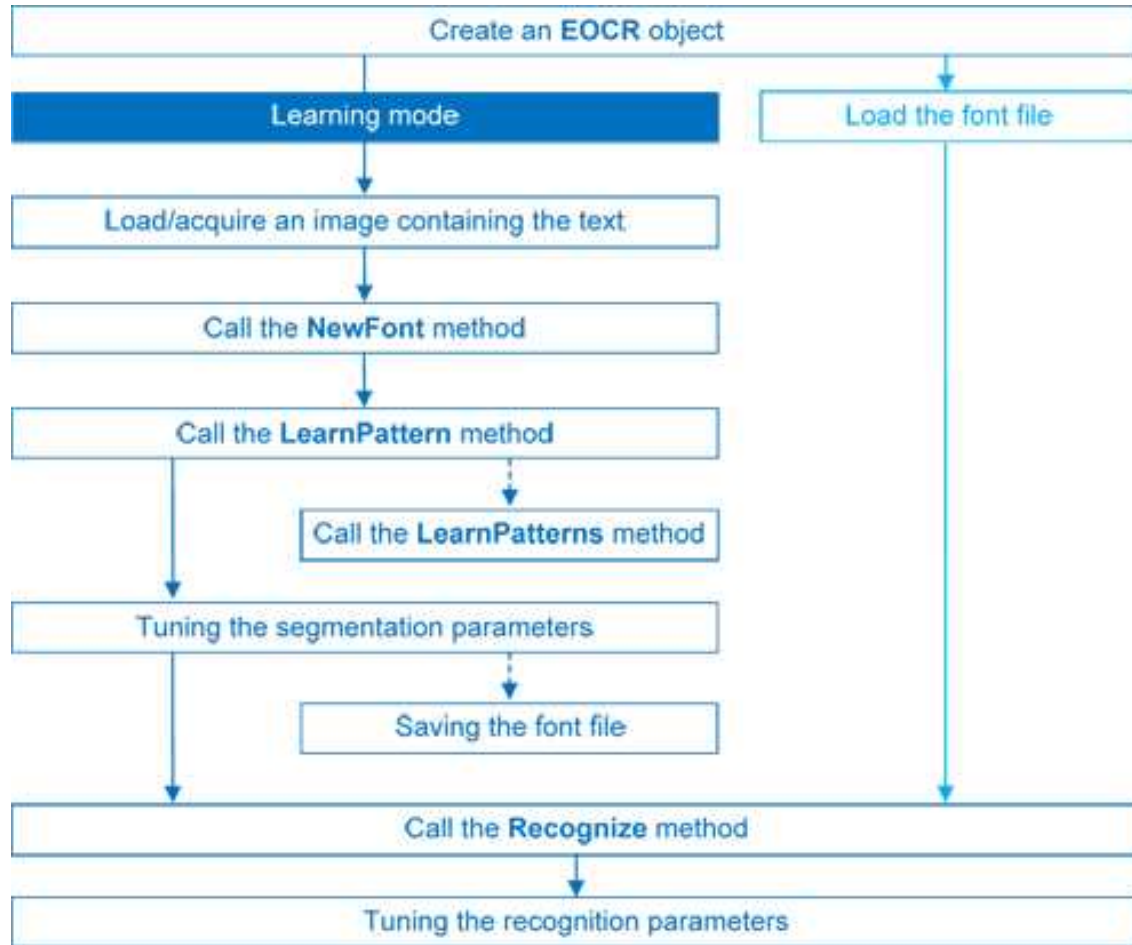


3. Character isolation



4. Character recognition

Workflow



Learning Process

You can learn characters to create a font file if required.

Characters are presented one by one to EasyOCR which analyzes them and builds a database of characters called a font. Each character has a numeric code (usually its ASCII code) and belongs to a [character class](#) (which may be used in the recognition process).

Font files are created as follows:

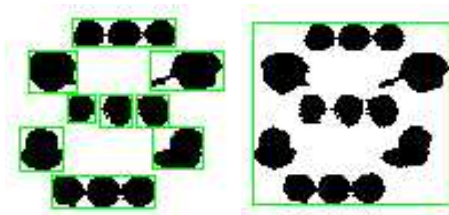
1. [NewFont](#) clears the current font.
2. [LearnPattern](#) or [LearnPatterns](#) adds the patterns from the source image to the font. Patterns are ordered by their index value, as assigned by the [FindAllChars](#) process. The patterns in a font are stored as a small array of pixels, by default 5 pixels wide and 9 pixels high. This size can be changed before learning, using parameters [PatternWidth](#) and [PatternHeight](#).
3. [RemovePattern](#) removes unwanted patterns (optional).

4. `Save` writes the contents of the font to a disk file with parameter values: `NoiseArea`, `MaxCharWidth`, `MaxCharHeight`, `MinCharWidth`, `MinCharHeight`, `CharSpacing`, `TextColor`.

Segmenting

Segmenting

1. EasyOCR analyses the blobs to locate the characters and their bounding box, using one of two [segmentation modes](#):
 - **keep objects** mode: one blob corresponds to one character.
 - **repaste objects** mode: the blobs are grouped into characters of a nominal size. This is useful when characters are broken or made up of several parts. When a blob is too large to be considered a single character, it can be split automatically using `CutLargeChars`.



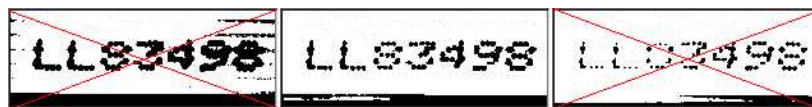
Character segmentation by blob grouping

2. Filters remove very large and very small unwanted features.
3. EasyOCR processes the character image to normalize the size into a bounding box, extracts relevant features, and stores them in the font file. The patterns in a font are stored as arrays of pixels defined by `PatternWidth` and `PatternHeight` (by default 5 pixels wide and 9 pixels high).

Segmentation parameters

Segmentation parameters must be the same during learning and recognition. Good segmentation improves recognition.

- The `Threshold` parameter helps separate the text from the background. A too high value thickens black characters on white background and may cause merging, a too small value makes parts disappear. If the lighting conditions are very variable, automatic thresholding is a good choice.



Too high threshold value (left), Threshold adjustment (middle), Too low threshold value (right)

- `NoiseArea`: Blob areas smaller than this value are discarded. Make sure small character features are preserved (i.e., the dot over an "i" letter).

- **MaxCharWidth, MaxCharHeight:** Maximum character size. If a blob does not fit in a rectangle with these dimensions, it is discarded or split into several parts using vertical cutting lines. If several blobs fit in a rectangle with these dimensions, they are grouped together.
- **MinCharWidth, MinCharHeight:** Minimum character size. If a blob or a group of blobs fits in a rectangle with these dimensions, it is discarded.
- **CharSpacing:** The width of the smallest gap between adjacent letters. If it is larger than **MaxCharWidth** it has no effect. If the gap between two characters is wider than this, they are treated as different characters. This stops thin characters being incorrectly grouped together.
- **RemoveBorder:** Blobs near image/ROI edges cannot normally be exploited for character recognition. By default, they are discarded.

Recognition

Recognition

The characters are compared to a set of patterns, called a **font**. A character is recognized by finding the best match between a character and a pattern in the font. After the character has been located, it is normalized in size (stretched to fit in a predefined rectangle) for matching. The normalized character is compared to each normalized template in the font database and the best matches are returned.

1. **Load:** reads a pre-recorded font from a disk file.
2. **BuildObjects:** The image is segmented into **objects** or blobs (connected components) which help find the **characters**. This step can be bypassed if the exact position of the characters is known. If the character isolation process is bypassed, you must specify the known locations of the characters: **AddChar** and **EmptyChars**.
3. **FindAllChars:** selects the objects considered as characters and sorts them from top to bottom then left to right.
4. **ReadText:** performs the matching and filters characters if the marking structure is fixed or a character set filter was provided.

Character recognition: The characters are compared to a set of patterns, called a **font**.

The best match is stretched to fit in a predefined rectangle and compared to each normalized template in the font database.

A **Character set filter** can improve recognition reliability and run time by restricting the range of characters to be compared. For instance, if a marking always consists of two uppercase letters followed by five digits, the last of which is always even, it is possible to assign each character a class (maximum 32 classes) then set the character filter to allow the following classes at recognition time: two uppercase, four even or odd digits, one even digit.

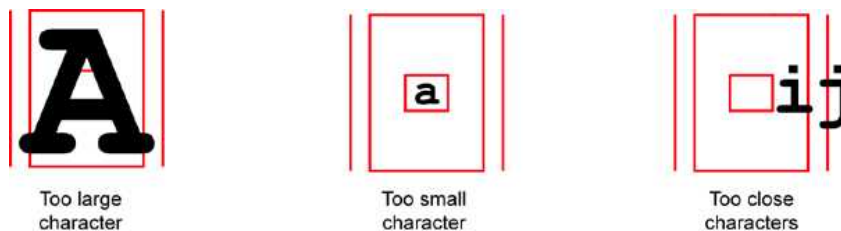
Steps 2 to 4 can be repeated at will to process other images or ROIs. The **Recognize** method can be used as well.

Additional information, such as the geometric position of the detected characters, can be obtained using: **CharGetOrgX**, **CharGetOrgY**, **CharGetWidth**, **CharGetHeight**, ...

CompareAspectRatio makes character and font comparison sensitive to the difference between narrow and wide characters. It improves recognition when characters look like each other after size normalization.

Recognition parameters

- **MaxCharWidth**, **MaxCharHeight**: if a blob does not fit within a rectangle with these dimensions, it is not considered as a possible character (too large) and is discarded. Furthermore, if several blobs fit in a rectangle with these dimensions, they are grouped together, forming a single character. The outer rectangle size should be chosen such that it can contain the largest character from the font, enlarged by a small safety margin.
- **MinCharWidth**, **MinCharHeight**: if a blob or a group of blobs does fit in a rectangle with these dimensions, it is not considered as a possible character (too small) and is discarded. The inner rectangle size should be chosen such that it is contained in the smallest character from the font, shrunk by a small safety margin.
- **RemoveNarrowOrFlat**: Small characters are discarded if they are narrow **or** flat. By default they are discarded when they are both narrow **and** flat.
- **CharSpacing**: if two blobs are separated by a vertical gap wider than this value, they are considered to belong to different characters. This feature is useful to avoid the grouping of thin characters that would fit in the outer rectangle. Its value should be set to the width of the smallest gap between adjacent letters. If it is set to a large value (larger than **MaxCharWidth**), it has no effect.
- **CutLargeChars**: when a blob or grouping of blobs is larger than **MaxCharWidth**, it is discarded. When enabled, the blob is split into as many parts as necessary to fit and the amount of white space to be inserted between the split blobs is set by **RelativeSpacing**. This is an attempt to separate touching characters.
- **RelativeSpacing**: when the **CutLargeChars** mode is enabled, setting this value allows specifying the amount of white space that should be inserted between the split parts of the blobs.



Invalid recognition settings

Advanced tuning

These recognition parameters can be tuned to optimize recognition:

CompareAspectRatio: when this setting is on, EasyOCR is less tolerant of size and takes into account the measured aspect ratio. Using this mode improves the recognition when characters look similar after size normalization as it enforces the difference between narrow and wide characters.

Filtering the characters (in the **ReadText** method), can be used if the marking structure is fixed.

When objects are larger than the **MaxCharWidth** property, they can be split into as many parts as needed, using vertical cutting lines.

ESegmentationMode, **character isolation mode** defines how characters are isolated:

- **Keep objects** mode: a character is a blob; no attempt is made to group blobs, thus damaged characters cannot be handled and small features such as accents and dots may be discarded by the minimum character size criterion.

- **Repaste objects** mode: blobs are grouped to form distinct **characters** if they fit in the maximum character size and are not separated by a vertical gap, thus preserving accents and dots.

0.5. EasyOCR2 - Reading Texts (Improved)

Workflow

[Reference](#) | [Code Snippets](#)

EasyOCR2

EasyOCR2 is an optical recognition library designed to read short texts such as serial numbers, expiry dates or lot codes printed on labels or on parts.

It can use an innovative segmentation method to detect blobs in the image, and then places textboxes over the detected blobs following a user-defined topology (number of lines, words and characters in the text). These methods support text rotation up to 360 degrees, can handle non-uniform illumination, textured backgrounds, as well as dot-printed or fragmented characters.

A character type (letter / digit / symbol) can be specified for each character in the text, improving recognition rate and speed.

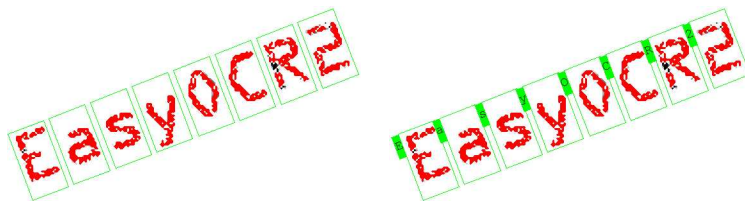
You can perform the recognition in two different ways:

- Use a pre-trained classifier powered by Deep Learning technologies.
- Or use a character database built from sample images or from a TrueType font (.ttf) file.

Text recognition with EasyOCR2 follows four phases:



Input image (left) and image segmentation (right)



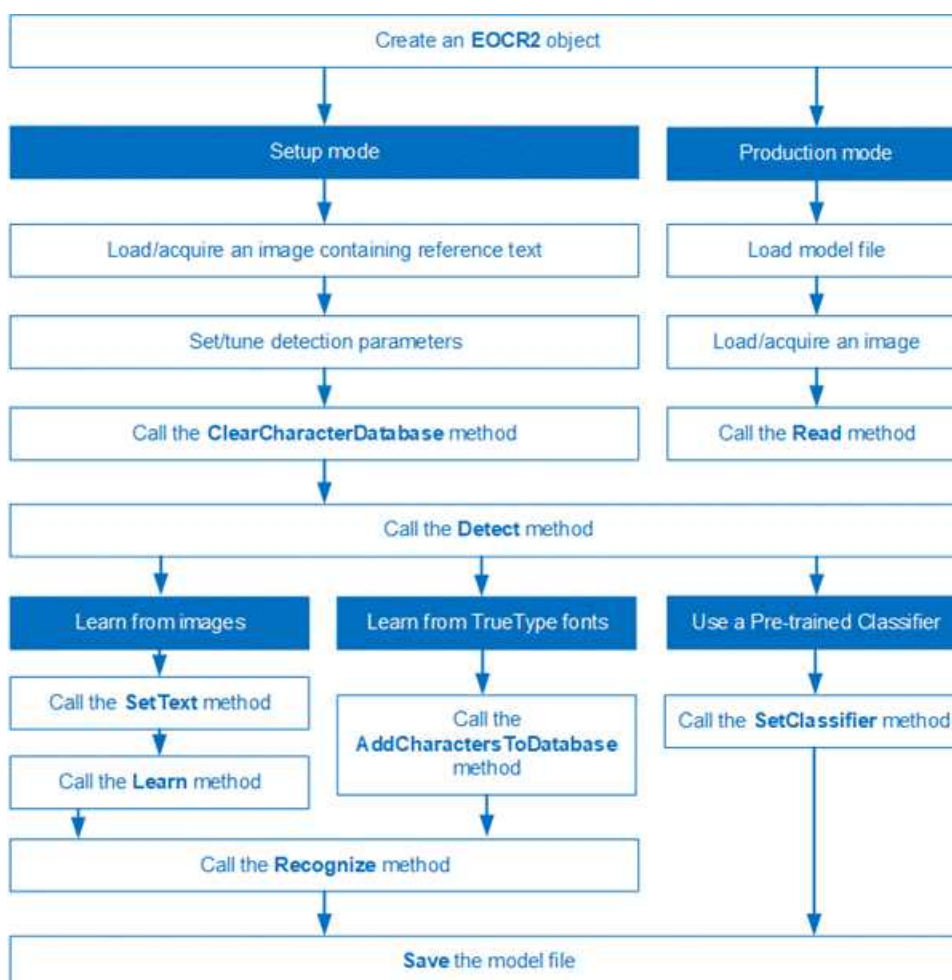
Fitting textboxes (left) and recognition (right)

EasyOCR2 vs EasyOCR

EasyOCR2 will give better results than EasyOCR when dealing with:

- Unknown text rotation
- Dotted or fragmented characters
- Non-uniform illumination or textured backgrounds
- Complex text topologies
- When TrueType font files that match the text to be read are available, EasyOCR2 allows the user to use those font files directly for recognition, while EasyOCR does not.
- EasyOCR2 can perform recognition without any preliminary training using the provided pre-trained classifiers.

Workflow



Detection

Detection

EasyOCR2 finds characters in an image as follows:

1. EasyOCR2 segments the image, finding blobs that represent (parts of) the characters.
2. Blobs that are too large or too small to be considered as parts of a character are filtered out.
3. EasyOCR2 fits character boxes to the detected blobs according to a given [topology](#) and [detectionMethod](#).
 - The topology describes the structure of the text in the image, defining the number of lines, the number of words per line and the number of characters per word.
 - If the topology is not required, EasyOCR2 fits boxes to the blobs as best as it can.
4. EasyOCR2 extracts the pixels inside each character box from the image.

The resulting character-images can be used to learn or recognize the characters.

A workflow detecting text in an image could be as follows:

- a. Set the required detection parameters.
- b. Alternatively, call [Load](#) to read a pre-made model (.o2m) file containing detection parameters from disk.
- c. Call [Detect](#) to extract the text from the image.

The method [Detect](#) will return an [EOCR2Text](#) structure that contains a textbox and a bitmap image for each character, hierarchically stored in [EOCR2Line](#) -> [EOCR2Word](#) -> [EOCR2Char](#) structures.

See example in code snippet: "[Detecting Characters](#)" on page 115



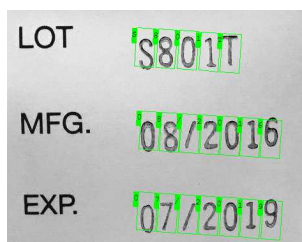
The image shows the text 'FIXED WIDTH' in a fixed-width font. Each character is enclosed in a green rectangular bounding box, demonstrating uniform spacing between characters.

An example of a fixed-width font, processed with the [detectionMethod](#) '[EOCR2DetectionMethod_FixedWidth](#)'

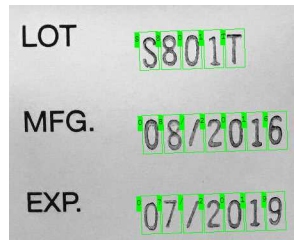


The image shows the text 'PROPORTIONAL' in a proportional font. Each character is enclosed in a green rectangular bounding box, demonstrating variable spacing between characters.

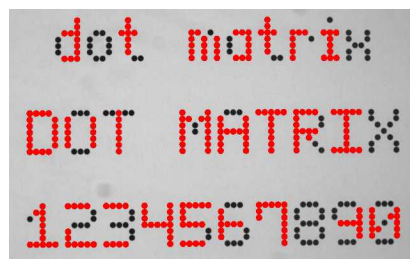
An example of a proportional font, processed with the [detectionMethod](#) '[EOCR2DetectionMethod_Proportional](#)'



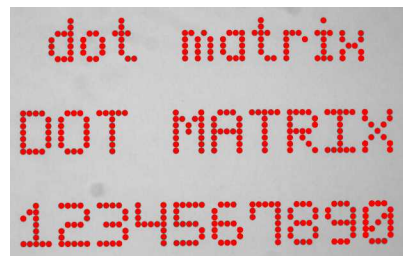
The text angle estimate for this image is slightly off when `NumDetectionPasses=`➔



The text angle estimate is better when `NumDetectionPasses=2`



For this dotted text, setting `CharsMaxFragmentation` to 0.1 leads to incomplete segmentation results



Setting `CharsMaxFragmentation` to 0.01 gives better segmentation results

Detection parameters

Required parameters

- The parameter `EnableTopology` indicates if the parameter `Topology` is required. In simple cases, the topology may not be necessary.
- The parameter `Topology` tells the box-fitting method how to structure the textboxes it fits to the detected blobs. Using a modified version of Regex expressions, the topology determines the number of lines in the text, the number of words per line and the number of characters per word. The section **Recognition Parameters** contains an extensive explanation of the syntax for the Topology.

- The parameter `CharsWidthRange` tells the segmentation and detection methods how wide the characters in the image can be.
- The parameter `CharsHeight` tells the segmentation and detection methods how high the characters in the image can be.
- The parameter `TextPolarity` tells the segmentation method whether it should look for light characters on a dark background or vice versa.

Advanced parameters for segmentation (optional):

- The parameter `SegmentationMethod` selects the algorithm used for segmentation.
 - The setting `E0CR2SegmentationMethod_Global` is faster and suited for clear background.
 - The setting `E0CR2SegmentationMethod_Local` (default) is more complex and suited for non uniform background.
- The `CharsMaxFragmentation` parameter tells the segmentation algorithm how small blobs can be to be considered (part of) a character. The minimum allowed area of a blob is given by:

$$\text{minArea} = \text{CharsMaxFragmentation} * \text{CharsHeight} * \text{min}(\text{CharsWidthRange})$$

- This parameter should be set between 0 and 1, the default setting is 0.1.

Advanced parameters for local segmentation (optional):

- The `MaxVariation` parameter determines how stable a blob in the image should be in order to be considered a potential character.
 - A region with clearly defined edges is generally considered stable while a blurry region is not. A high setting allows detection of blobs that are more unstable, a low setting allows only very stable blobs.
 - This parameter should be set between 0 and 1, the default setting is 0.25.
- The `DetectionDelta` parameter determines the range of grayscale values used to determine the stability of a blob.
 - A low setting will make the algorithm more sensitive to noise; a high setting will make the algorithm insensitive to blobs with low contrast to the background.
 - This parameter should be set between 1 and 127, the default setting is 12.

Advanced parameters for global segmentation (optional):

- The parameter `EnableSecondPassGlobalSegmentation` performs the segmentation twice during the first pass to have more accurate results when the text background is not just plain.

Advanced parameters for detection (optional)

- If the topology is required, the parameter `DetectionMethod` selects the algorithm used for fitting.
 - The setting `E0CR2DetectionMethod_FixedWidth` (default) is optimized for texts with fixed width fonts (including dotted text).
 - The setting `E0CR2DetectionMethod_Proportional` is optimized for texts with proportional fonts.

- The `TextAngleRange` parameter tells the box-fitting method how the text in the image is oriented. It will test the following range of rotation angles:

$$\min(\text{TextAngleRange}) \leq \text{angle} \leq \max(\text{TextAngleRange})$$

where angles are defined with respect to the horizontal. The unit for the angles (degrees/radians/revolutions/grades) can be set using `easy::SetAngleUnit()`.

- The default setting for this parameter is [-20, 20] degrees.
- The parameter `NumDetectionPasses` determines how many passes are made to fit textboxes to the detected blobs. The initial pass will fit textboxes to all detected blobs. Subsequent passes will select only those blobs that are covered by the textboxes from the previous pass and fit textboxes to that subset of blobs, potentially resulting in a more optimal fit.
 - This parameter should be set to either 1 or 2, the default setting is 1.

Advanced parameters, specific for the setting `EOCR2DetectionMethod_FixedWidth`

- The `RelativeSpacesWidthRange` parameter tells the box-fitting method how wide the spaces between words may be. It will test the following range of spaces:

$$\min(\text{SpacesWidthRange}) * \text{charWidth} \leq \text{space} \leq \max(\text{SpacesWidthRange}) * \text{charWidth}$$

- The lower bound of this parameter is also used when the topology is not required.
- The parameter `CharsWidthBias` biases the optimization toward wider or narrower character boxes.
- The parameter `CharsSpacingBias` biases the optimization toward smaller or larger spacing between characters boxes.

Advanced parameters, specific for the setting `EOCR2DetectionMethod_Proportional`:

- The parameter `EnableCutLargeCharacter` tells if the detection should try to split too wide segmented blobs into different characters.
 - This parameter is also used when the topology is not required.

Advanced parameters, specific when the topology is not required:

- The parameter `EnableOffSizeCharacter` tells if the detection should allow or not the detection of characters whose size (width and height) is out of the size parameters if they are in the vicinity of characters in valid size range.

Additional remarks

- When the setting `EOCR2DetectionMethod_FixedWidth` is selected, all character boxes will have the same width and they do not necessarily have to fit tightly around the characters.
- When the setting `EOCR2DetectionMethod_Proportional` is selected, the character boxes will fit tightly around the characters, if any character falls outside the range of allowed character widths, the detection will fail.

Learning

In order to recognize characters, EasyOCR2 can use a database of known reference characters. You can generate this character database from images and/or from TrueType system fonts.

A workflow to build a character database could be as follows:

1. Set the required detection parameters or call [Load](#) to read the model (.o2m) file from disk.
2. Optionally, call [ClearCharacterDatabase](#) to clear the current character database.
3. Call [Detect](#) to extract the text from the image.
4. Call [SetText](#) in the extracted text structure to set the correct value for each character.
5. Call [Learn](#) to add the detected characters and their correct value to the current character database.
6. Call [SaveCharacterDatabase](#) to save the current character database to disk.
7. Alternatively, call [Save](#) to save the model file to disk, including the detection parameters and the created character database.

See example in code snippet: "[Learning Characters](#)" on page 116

Recognition

Recognition

EasyOCR2 recognizes characters using a pre-trained classifier or a classifier that is trained on the character database. For each input character, the classifier will calculate a score for all candidate outputs, the candidate with the highest score will be returned as the recognition result. Through the [Topology](#) parameter, prior information about each character can be passed to the classifier, reducing the number of candidates and improving the recognition rate.

The production workflow for recognizing text from images could be as follows:

- Call [Load](#) to read the model (.o2m) file from disk. The model file contains all detection parameters, as well as the topology and the reference character database.
- Load or acquire the image.
- Call [Read](#) to detect and recognize the characters.
- Alternatively, call [Detect](#) to extract the text from the image, followed by [Recognize](#) to recognize the extracted text. This allows the user to modify elements of the detected text before recognition if so desired.

The methods [Read](#) and [Recognize](#) will return a string with the recognition results. To access more in-depth information about the results, one may call [ReadText](#). This returns an [EOCR2Text](#) structure that contains the coordinates and sizes of each textbox as well as a bitmap image and a list of recognition scores for each character.

See example in code snippet: "[Reading Using EOOCR2 Model File](#)" on page 118

Recognition parameters

The **Classifier** parameter specifies the classifier used by **EOCR2** for recognition. By default, its value is **EOCR2Classifier_**
DatabaseClassifier and it means that it uses the current Character Database. Other values represent pre-trained classifiers for different context.

The **Topology** parameter specifies the structure of the text (number of lines/words/characters) as well as the type of characters in the text. The recognition method will limit the number of candidates for each character based on the given topology.

It uses modified regular expression wildcards:

- “.” (dot) represents any character (not including a space).
- “L” represents an alphabetic character.
 - “Lu” represents an uppercase alphabetic character.
 - “Ll” represents a lowercase alphabetic character.
- “N” represents a digit.
- “P” represents the punctuation characters: ! “ # % & ‘ () * , - . / : ; < > ? @ [\] _ { | } ~
- “S” represents the symbols: \$ + - < = > | ~
- “\n” represents a line break.
- “ ” (space) represents a space between two words.

Combinations can be made, for example: [LN] represents an alphanumeric character. To specify multiple characters, simply add {n} at the end for n characters. If the amount of characters is uncertain, specify {n,m} for a minimum of n characters and a maximum of m characters.

The topology “[LuN]{3,5}PN{4} \n .{5} LL” represents a text comprised of 2 lines:

- The first line has 1 word composed of 3 to 5 uppercase alphanumeric characters, followed by a punctuation character and 4 digits.
- The second line has 2 words. The first word comprises 5 wildcard characters, the second word has 2 letters (uppercase or lowercase).

The topology “L{3}P N{6} \n L{3}P NNPN{4}” represents a text with 2 lines:

- The first line has 2 words. The first word has 3 uppercase letters followed by a punctuation mark, the second word has 6 digits.
- The second line also has two words. The first word has 3 uppercase letters followed by a punctuation mark. The second word has 2 digits, followed by a punctuation mark and 4 additional digits.

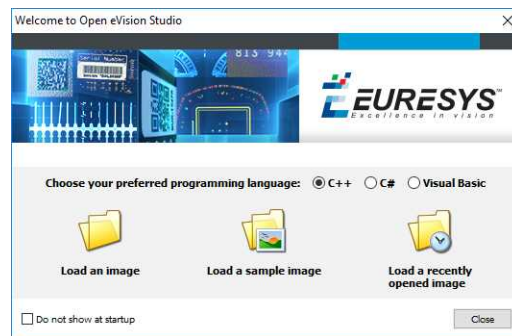
The topology “. {10} \n .{7} \n .{5} .{5} \n .{5} .{7}” represents a text with 4 lines:

- The first line contains a single word of 10 (ASCII) characters
- The second line contains a single word of 7 characters
- The third line contains two words, each of 5 characters.
- The fourth line contains two words of 5 and 7 characters respectively.

1. Using Open eVision Studio

1.1. Selecting your Programming Language

When you start Open eVision Studio for the first time, the following welcome screen is displayed:



1. Select your programming language.



TIP

Your selection is saved and your programming language will be automatically selected next time you start Open eVision Studio.



NOTE

When you change your programming language, any script present in the scripting window is automatically deleted and the window content is reset.

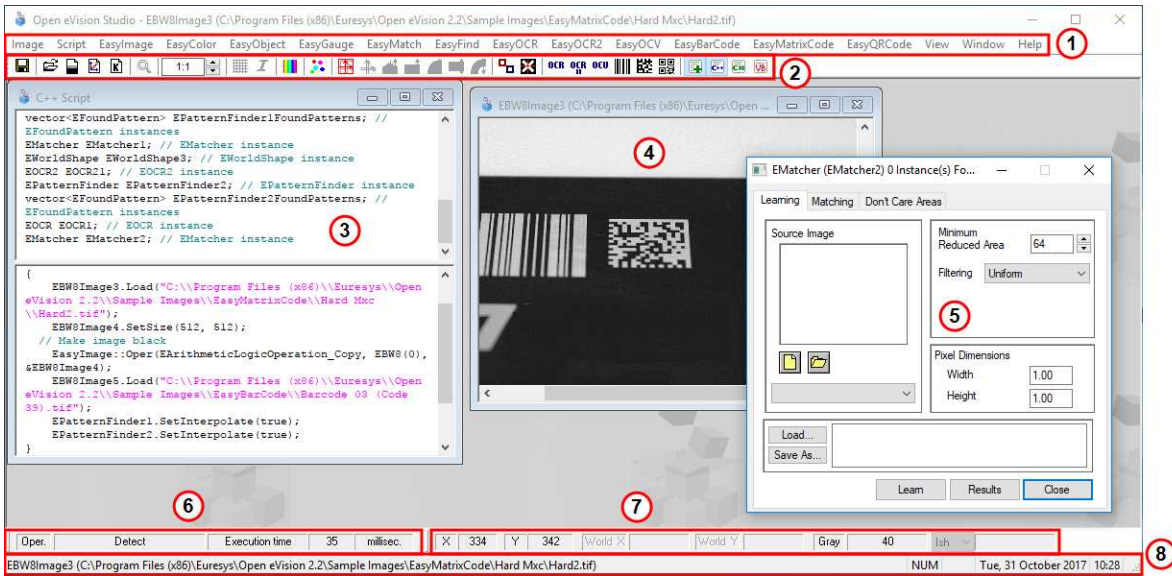
2. Click on one of the **Load** buttons to already load one or several images for later processing.
3. Check the **Do not show at startup** box to hide this welcome screen next time you start Open eVision Studio.



TIP

To access this welcome screen at any time, and change this setting, go to the **Help > Welcome Screen** menu.

1.2. Navigating the Interface



Open eVision Studio graphical user interface (GUI) is organized as follows:

1. The *main menu bar* gives you access to the functions and tools of all libraries.



TIP

Open eVision Studio does not require any license and allows you to test all libraries. Of course, if you copy code from Open eVision Studio in your own application but you do not have the required license, you will receive a "missing license" error at run-time.

2. The *main toolbar* gives you quick access to main Open eVision objects such as images, shapes, gauges, bar codes, matrix codes...
3. The *script window* displays the code, in the programming language you selected, corresponding to the actions you perform in Open eVision Studio. You can save or copy this code in your own application at any time.
4. The *image windows* display the open images that you can process using the libraries and tools.
5. The *tool windows* enable you to easily configure all the available tools. The corresponding settings are automatically added in the script window for easy reuse.



TIP

Most tool windows are floating and you can easily move them outside the Open eVision Studio main window to make better use of your screen size.

6. The *execution time bar* displays the precise time taken for the execution of the selected functions (measured in milliseconds or microseconds) on your computer. This accurate measurement helps you to evaluate the performance of your application.
7. The *color toolbar* displays current information such as the X and Y coordinates of the cursor on an image and the corresponding pixel value.
8. The *status bar* displays general information about the application such as the active image file path...

1.3. Running Tools on Images

Step 1: Selecting a Tool

When you use Open eVision Studio, the first step is to select the library and the tool you want to use on your image.

To do so:

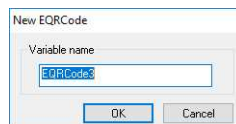
1. In the main menu bar, click on the library you want to use.
2. Click on the tool you want to use.



TIP

All libraries (except EasyImage, EasyColor and EasyGauge) expose only one tool named *New Xxx Tool*. Some of these libraries also expose additional functions.

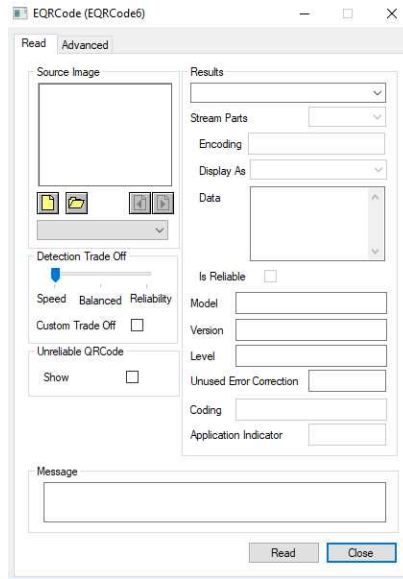
3. In the dialog box, enter a *Variable name* for the variable that is automatically created and that will contain the result of the processing.



Example of variable creation dialog box for EasyQRCode

4. Click OK.

The selected tool dialog box opens.



Example of variable creation dialog box for EasyQRCode


The next step is "[Step 2: Opening an Image](#)" on page 84.

Step 2: Opening an Image

Once you have selected your library and your tool, you need to open an image to apply this tool.

In the **Source Image** area of the selected tool dialog box:

1. Open an image:

- Click on the  **Open an Image** button and select one or several (using SHIFT and CTRL) images on your computer.
- Or select one of the images (or one of the ROIs, if any) already open in the drop-down list.



NOTE

You can select only images with an appropriate file format (JPG, PNG, TIFF or BMP) and in 8- and/or 24-bit depending on the library.



- ### 2. If you selected several images, activate one with the **Load Previous** or **Load Next** buttons.

The tool is automatically applied on any loaded image and, at this stage, the result is displayed based on the tool default settings.

The next step is "[Step 3: Managing ROIs](#)" on page 85.

Step 3: Managing ROIs

In some cases, most often to decrease the processing time or to single-out the object you want to read, you do not want to process the whole image but only one or several well defined rectangular parts of this image, or ROIs (Regions Of Interest).



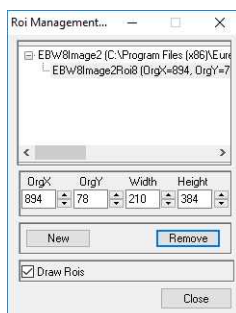
TIP

In Open eVision, ROIs are attached to an image and exist only as long as the parent image is available.

Creating a ROI

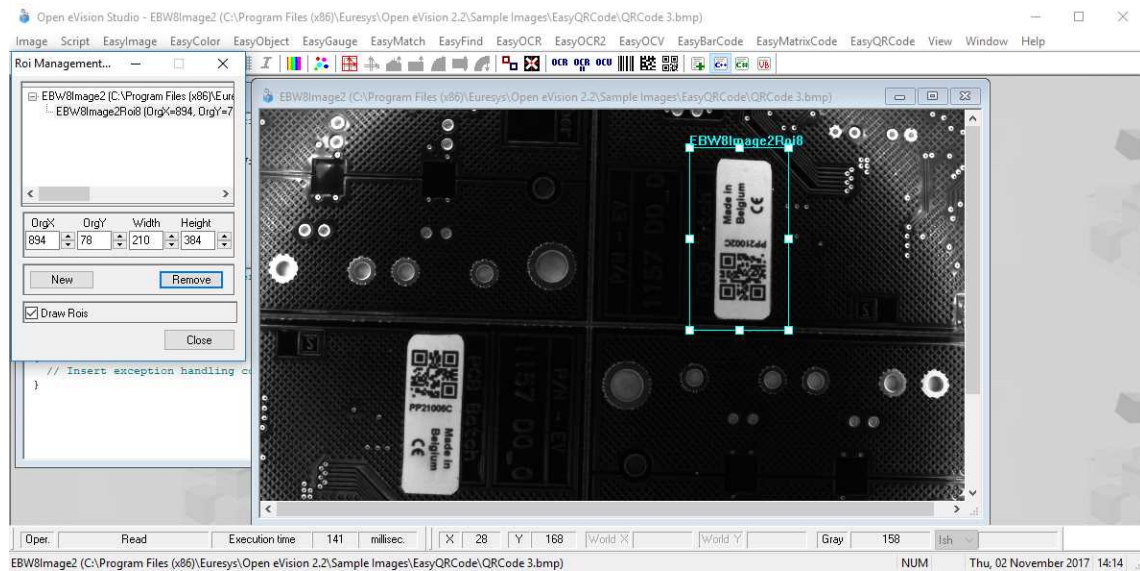
1. Open the image:
 - If the image is already open, activate the corresponding image window.
 - If the image is not open yet, go to the main menu: **Image > Open...** to open one.
2. To create an ROI, go to the main menu: **Image > ROI Management...**

The **ROI Management** window is displayed as illustrated below.



3. Select the image in the tree.
4. Click on the **New** button.
5. In the dialog box, enter a **Variable name** for the new ROI.

The ROI is represented as a color rectangle on your image as illustrated below.



6. Drag the ROI corner and side handles to move it to the required position.

7. Click on the Close button to close the ROI Management window.

The next step is "[Step 4: Configuring the Tool](#)" on page 87.

Managing ROIs

You can add, change and remove ROIs.



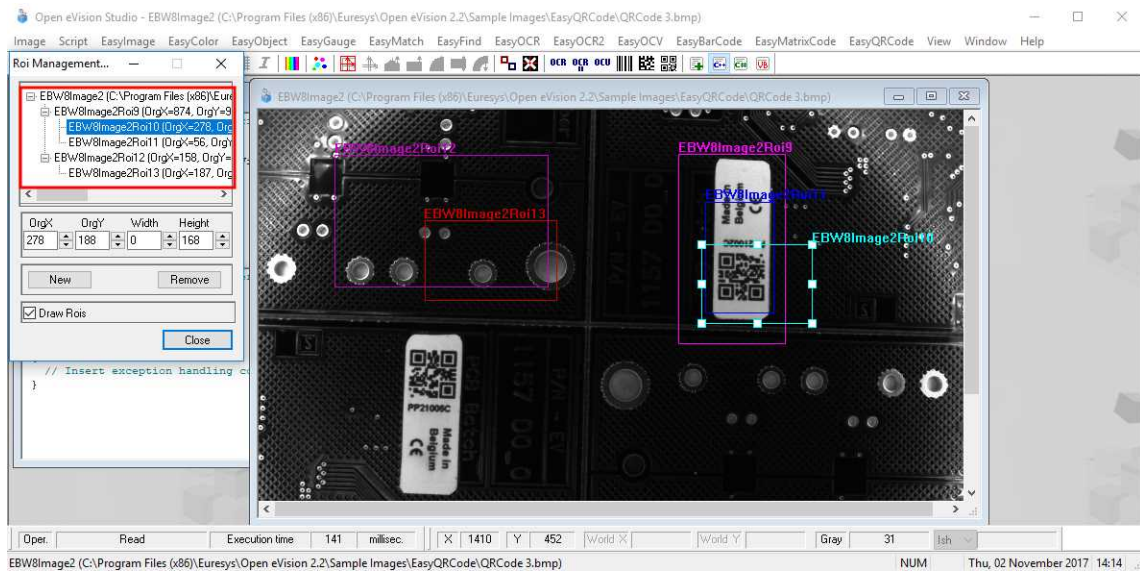
TIP

An image can have several ROIs. Each ROI can be attached directly to the image (meaning that its position is relative to the image) or to another ROI (meaning that its position is relative to this 'parent' ROI).

1. To manage ROIs, go to the main menu: Image > ROI Management...

The ROI Management window is displayed with the ROI relation tree as illustrated below.

If the Draw RoIs box is checked, all ROIs are displayed on the image with a different color.



2. Select an ROI in the ROI relation tree.
3. Drag the ROI corner and side handles to change the position and size of the selected ROI (as well as the position of all ROIs attached to it if any).
4. Click on the **New** button to add a new ROI attached to the selected ROI.



TIP

Select the image at the top of the ROI relation tree to attach the ROI directly to the image.

5. Click on the **Remove** button to delete the selected ROI (and all ROIs attached to it if any).
6. Click on the **Close** button to close the **ROI Management** window.

Step 4: Configuring the Tool

Once your image, including its ROIs if you created some, is ready, you need to configure your tool.

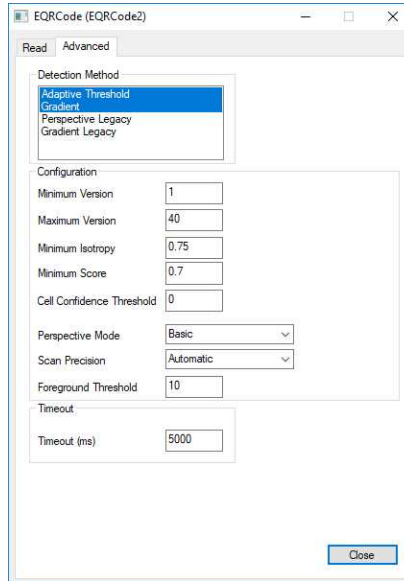
In the tool window:

1. Open the various tabs.



TIP

When you create a new tool, all parameters are set with their default value.



Example of the parameter tab of an EasyQRCode tool

2. In each tab, set the value of the parameters as desired.

Please refer to the "Functional Guide" and to the "Reference Manual" for detailed information about the parameters, their function and their default value.

For specific actions such as learning or using gauges, please refer to the "Functional Guide".

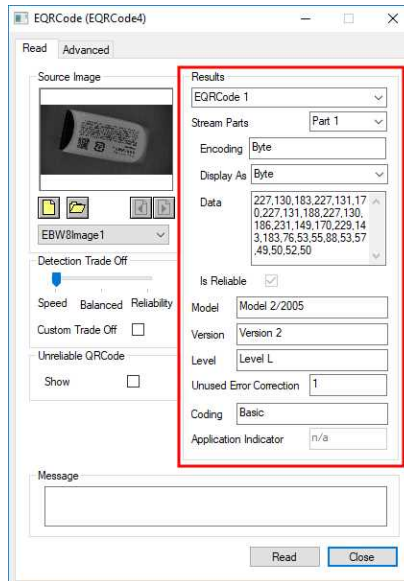
3. Run the tool and analyze the results as described in the next step "[Step 5: Running the Tool and Checking Execution Time](#)" on page 88.

Step 5: Running the Tool and Checking Execution Time

Once your tool parameters are set, run your tool and, if desired, check the execution time on your computer.

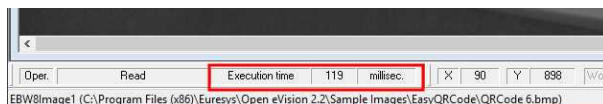
In the tool window:

1. Click on the **Read**, **Detect**, **Results** or **Execute** button (depending on the library function), to run the tool on the selected image.
2. Check the results on the image and in the Results field or area as illustrated below.



Example of results after reading a QRCode

3. If you do not have the expected results:
 - Try to change your parameters (start with default values then change one parameter at a time).
 - If your image is not good enough, try to enhance it as described in .
4. Check the execution time in the execution time bar at the bottom left of the main Open eVision Studio window.



The execution time



TIP

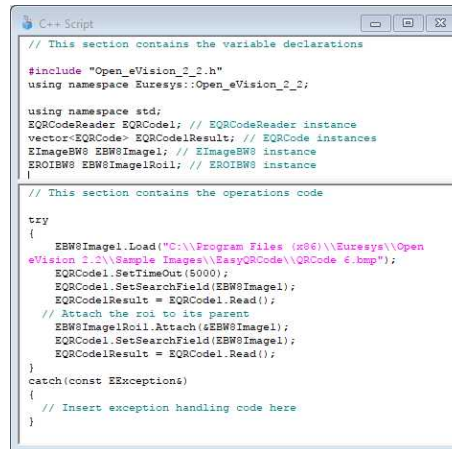
The execution time is the actual time that the processing took as measured on your computer. It depends your computer processor, memory, operating system... and, of course, on the processor load at the time of execution. Thus this execution time slightly varies from execution to execution.

5. To get a more representative execution time, click on the **Read**, **Detect**, **Results** or **Execute** button several times and calculate the mean execution time.
6. If your application requires that you reduce the execution time, try:
 - To change the tool parameters,
 - To add one or several ROIs on your image,
 - To enhance your image.

The next step is "[Step 6: Using the Generated Code](#)" on page 90.

Step 6: Using the Generated Code

By default, Open eVision Studio translates all the operations you perform in the interface into code in the language you selected as illustrated below.



```
C++ Script
// This section contains the variable declarations
#include "Open_eVision_2_2.h"
using namespace Euresys::Open_eVision_2_2;

using namespace std;
EQRCoderReader EQRCoder; // EQRCoderReader instance
vector<EQRCoder> EQRCoderResult; // EQRCoder instances
EImageBW8 EBW8Image1; // EImageBW8 instance
EROIWB8 EBW8Image1ROI; // EROIWB8 instance
}

// This section contains the operations code
try
{
    EBW8Image1.Load("C:\\Program Files (x86)\\Euresys\\Open
eVision 2.2\\Sample Images\\EasyQRCode\\QRCode 6.bmp");
    EQRCoder.SetTimeout(5000);
    EQRCoder.SetSearchField(EBW8Image1);
    EQRCoderResult = EQRCoder.Read();
    // Attach the roi to its parent
    EBW8Image1ROI.Attach(EBW8Image1);
    EQRCoder.SetSearchField(EBW8Image1);
    EQRCoderResult = EQRCoder.Read();
}
catch(const EExceptions)
{
    // Insert exception handling code here
}
```

Once your tool results suit you, you can save or copy this generated code to use it in your own application.

Copy and paste the code in your application

In the script window:

1. Select the code section you want to copy.
2. Right click on this code and click **Copy** in the menu.
3. Go to your development environment tool and paste the code in place.

Save the code

1. Go to the **Script** menu.
2. Click on **Save Script As....**
3. Enter a file name and path to save the code as a text file.

Manage the generated code

In the **Script** menu, you can:

- Select the programming language (please note that if you change the language, the script window content is automatically deleted).
- Activate or deactivate the **Script Code Generation**. Deactivate this option if you want to perform some operations without saving them as code.

1.4. Pre-Processing and Saving Images

When should you pre-process your images?

Of course, the best situation is to set up your image acquisition system to have good and easy to process images so the Open eVision tools run smoothly and efficiently.

If this is not possible or easy to achieve, you can pre-process your images or your ROIs to enhance and prepare them for the Open eVision tool you want to run.

Using the various available functions, you can adjust the gain and offset of your image, apply a convolution, threshold, scale, rotate and white balance your image, enhance contours... using EasyImage and EasyColor functions.

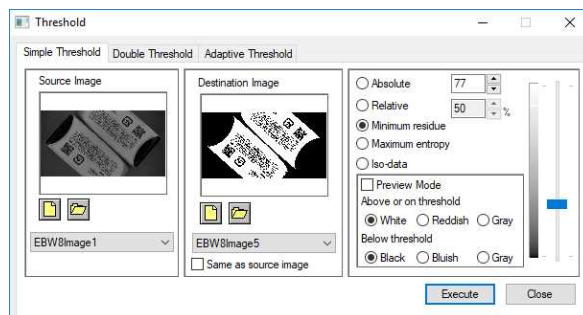
Pre-processing images

The difference between pre-processing an image and running tools is that the pre-processing generates a new image while the tools mainly extract and retrieve information from the image without changing it.

To pre-process an image or an ROI:

1. In the main menu bar, click on the library you want to use (EasyImage or EasyColor).
2. Click on the function you want to use.

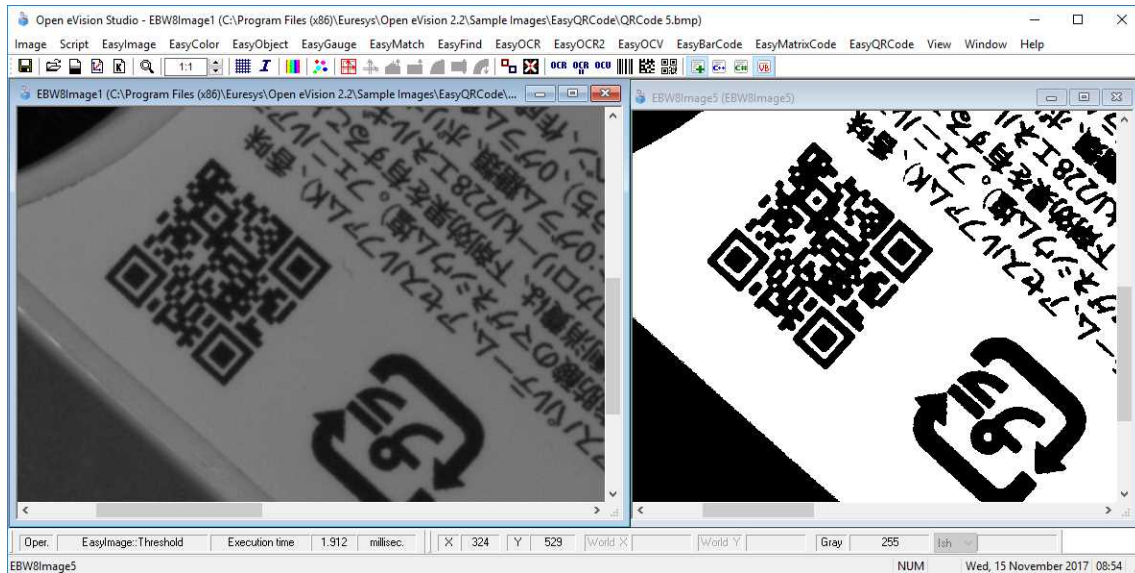
Most function dialog boxes are similar to the one illustrated below with 2 image selection areas and a parameter setting area.



Example of a pre-processing dialog box (Threshold with EasyImage)

3. If there are multiple versions for your selected function, open the corresponding tab.
4. In the Source Image area, open the source image (as described in "[Step 2: Opening an Image](#)" on page 84).
5. In the Destination Image area, open or create a new destination image.
6. Set your parameters.
7. Click on the Execute button.

The pre-processed image is available in the destination image as illustrated below.



Source and destinations images (Threshold with EasyImage)

8. If you want to use the destination image outside of Open eVision Studio, save it as described below.

Saving an image

1. Click on the image you want to save to makes its window active.
2. To open the save menu either:
 - Right-click in the image
 - Or open the main menu > Image
3. Click on Save as . . .
4. Select the file format (JPEG, JPEG2000, PNG, TIFF or Bitmap).
5. Enter a name and select a path.
6. Click on the Save button.

2. Tutorials

2.1. EasyBarCode

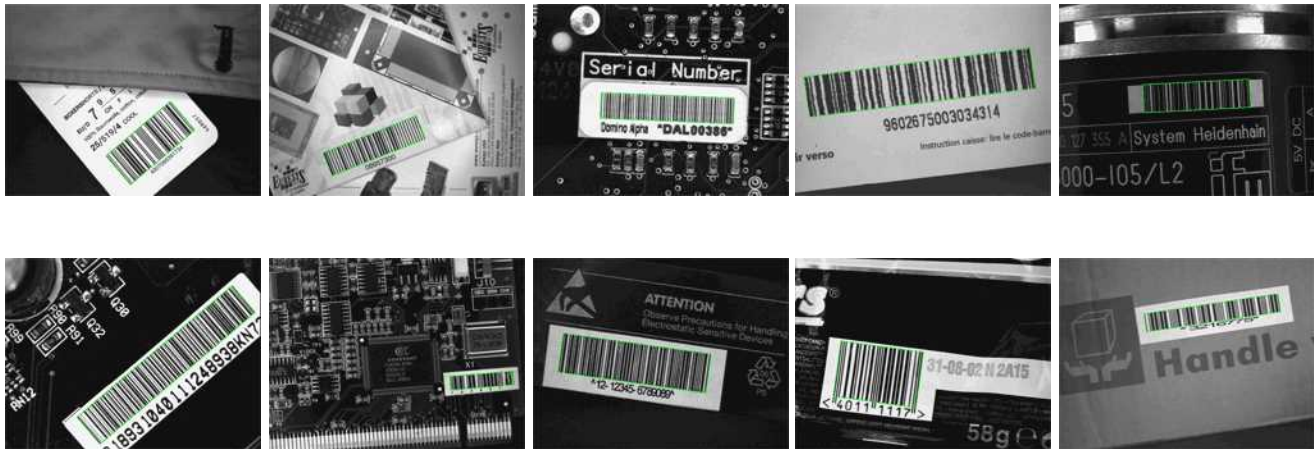
Reading Bar Codes Automatically

"Reading a Bar Code" on page 106

Objective

Following this tutorial, you will learn how to perform automatic reading of multiple bar codes.

You'll need first to load multiple source images (step 1). The reading is then automatically performed on each image (step 2).



Each bar code is automatically detected and decoded

Step 1: Load the source images

1. From the main menu, click EasyBarCode, then New BarCode Tool.
2. Keep the default variable name, and click OK.
3. In the AutoRead tab, click the Open icon of the Source Image area, and load the image files EasyBarCode\Barcode 0.tif to Barcode 9.tif. Use the shift key to select multiple files.
4. Keep the default variable name, and click OK. The last image appears.

Step 2: Read the bar codes automatically

1. The bar code is automatically detected and decoded. The graphic result appears on the image, while the data content and the corresponding symbology are displayed in the Decoded Symbology area. It is not necessary to click **Read** once a new image appears. However, clicking **Read** will insert the corresponding code into the script window.
2. In the **Results** tab, find more information about the bar code. As a bar code might have a meaning under different symbologies, all possible contents are listed by decreasing likeliness.
3. In the **AutoRead** tab, click the **Load Next** and **Load Previous** icons to browse through images 01 to 06.
The image files appear, and each bar code is automatically detected and decoded. The bar code properties are updated.
4. To decode the remaining bar codes, we have to enable the additional symbologies.
5. In the **Symbologies** tab, click the **Toggle All** button of the **Additional** area.
6. In the **AutoRead** tab, click the **Load Next** and **Load Previous** icons and browse the remaining images.

2.2. EasyMatrixCode

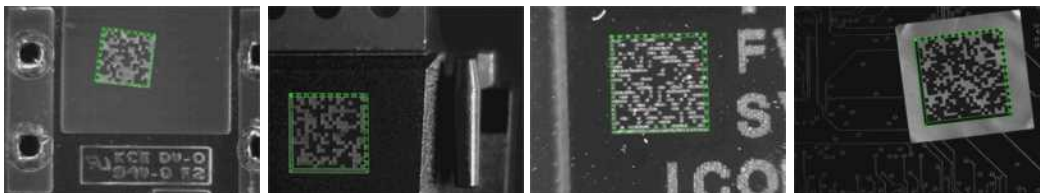
Reading Data Matrix Codes Automatically

"Automatic Reading" on page 109

Objective

Following this tutorial, you will learn how to use EasyMatrixCode to detect and decode automatically Data Matrix codes in multiple files.

You'll need first to load multiple source images (step 1). The reading is then automatically performed on each image (step 2). You can also grade the printing quality of each matrix code (step 3).



Each Data Matrix code is automatically detected and decoded

Step 1: Load the source images

1. From the main menu, click **EasyMatrixCode**, then **New MatrixCode Tool**.
2. Keep the default variable name for the new matrix code reader, and click **OK**.

3. In the Read tab, click the Open icon of the Source Image area, and load the image files `EasyMatrixCode\AutoRead\AutoRead 0.tif` to `AutoRead 04.tif`. Use the shift key to select multiple files.
4. Keep the default variable name for the new image, and click OK. The last image appears.

Step 2: Read the Data Matrix codes automatically

1. The Data Matrix code is automatically detected and decoded. The matrix code reference corner is highlighted with a bold cross mark. It is not necessary to click Read once a new image appears. However, clicking Read will insert the corresponding code into the script window.
2. In the Results area, find more information about the matrix code, such as the decoded string.
3. In the Read tab, click the Load Next and Load Previous icons. The image files appear, and each Data Matrix code is automatically detected and decoded. The matrix code properties are updated. If no Data Matrix code could be located in the image, an error message is displayed in the Message field.

Step 3: Grade Data Matrix code printing quality

1. In the Print Quality tab, select the Compute Grading check-box.
2. Click Apply.

For each printing quality parameter, the corresponding value and its grade equivalent appear. An A grade means a good quality, while an F grade indicates a poor one.

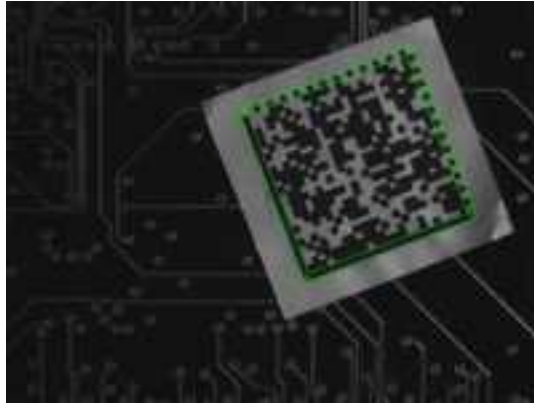
Learning a Data Matrix Code and Creating an EasyMatrixCode Model File

["Reading with Prior Learning" on page 109](#)

Objective

Following this tutorial, you will learn how to use EasyMatrixCode to learn a Data Matrix code, and save it as an EasyMatrixCode model file.

You'll need first to load a source image (step 1), and learn the matrix code (step 2). Then you'll save the learned matrix code as a new model file (step 3). You can also add new learned matrix codes to an existing model if needed (step 4).



The Data Matrix code has been learned

Step 1: Load the source image

1. From the main menu, click EasyMatrixCode, then New MatrixCode Tool.
2. Keep the default variable name for the new matrix code reader object, and click OK.
3. In the Learn tab, click the Open icon of the Source Image area, and load the image file EasyMatrixCode\Label\Label 4.tif.
4. Keep the default variable name for the new image object, and click OK.

Step 2: Learn the Data Matrix code

- In the Learn tab, click Learn.

The Data Matrix code is detected and decoded without error.

The graphical result appears on the image.

The properties of the learned matrix code are updated in the dialog box.

Step 3: Save the model file

1. In the Learn tab, click the Save As... button.
2. Type a file name for the new EasyMatrixCode model file. Its extension will be .mx2.
3. Click Save.

Step 4: Learning more Data Matrix codes

1. In the Read tab, click the Open icon of the source image area, and load the image file EasyMatrixCode\PCB Code\PCB Code 3.jpg.
2. Keep the default variable name for the new image object, and click OK.
3. An error message is displayed in the Message area of the Read tab. The matrix code can not be read, since the reader uses the model from the "Label 4" image. You need to learn the "PCB Code 3" matrix code, and add it to the model.

4. In the **Learn** tab, click **Learn More**. The Data Matrix code is detected and decoded without error. The graphical result appears on the image. The properties of the learned matrix code are updated in the dialog box.
5. Using **Learn More** rather than **Learn** involves that the "Label 4" model is not replaced by the "PCB Code 3" model, but both are now included in the same model. In the **Read** tab, the "PCB Code 3" matrix code is correctly read. Select the "Label 4" image in the drop-down list of the source image area. The "Label 4" matrix code is still read without error, which means that both learned matrix codes have been kept.
6. Finally, save the model again (refer to step 3). The new matrix code has been added.

2.3. EasyOCR

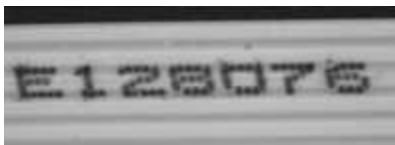
Learning Characters and Creating an EasyOCR Font

["Learning Characters" on page 114](#)

Objective

Following this tutorial, you will learn how to use EasyOCR to learn new characters and save them in an EasyOCR font.

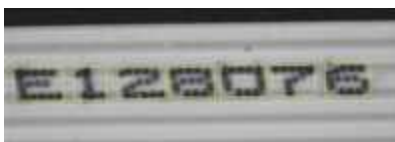
You'll need first to load a source image (step 1). Then you'll set the segmentation parameters to isolate each character (step 2). Each character will have to be learnt (step 3), and finally you'll save all the learnt characters as a font file (step 4). You can also add new characters to an existing font if needed (step 5).



Source image



The image is segmented so that all the characters are detected



All the characters have been learn

Step 1: Load the source image

1. From the main menu, click EasyOCR, then New OCR Tool.
2. Keep the default variable name for the new OCR object, and click OK.
3. In the Source Image tab, click the Open icon of the Source Image area, and load the image file EasyOCR\FlatCable\FlatCable.tif.
4. Keep the default variable name for the new image object, and click OK.

Step 2: Set segmentation parameters

1. Select the Segmentation Parameters tab, and move the red frame in the image above a character.
2. Tune each property to get a green bounding box around each character:
 - threshold value = 113
 - characters color = Black on White
 - min width = 36
 - min height = 31
 - spacing = 4
 - max width = 98
 - max height = 72
 - noise area = 9

Step 3: Learn new characters

1. Select the Learn tab, and click the character E in the image. You are then prompted to identify the character along with its class. Enter E in the character field, and select the 'E0crClass_Uppercase' class. Click OK. Whenever a character has been added to the current font, its bounding box turns yellow.
2. Click the character 1 in the image. Enter 1 in the character field, and select the 'E0crClass_Digit' class. Click OK.
3. Proceed with remaining characters.

Step 4: Save the EasyOCR font

- In the Font File tab, click the Save As... button. Type a file name for the new EasyOCR font file. Its extension will be .ocr. Finally, click Save.

Step 5: Add characters to an existing font

1. In the Source Image tab, click the Open icon of the Source Image area, and load the image file EasyOCR\FlatCable\FlatCable2.tif.
2. Keep the default variable name for the new image object, and click OK.
3. In the Recognition tab, click Execute. Characters 2 and 8 are read correctly, but A, W and G are not (low confidence score). They don't belong to the font.

4. Select the Learn tab, and learn the characters A, W, and G (refer to step 3).
5. Then save the font again (refer to step 4). The new characters have been added.

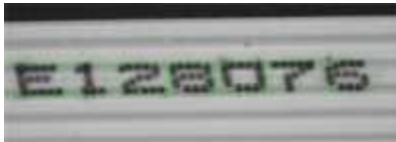
Recognizing Characters According to a Font

"Recognizing Characters According to a Font" on page 99

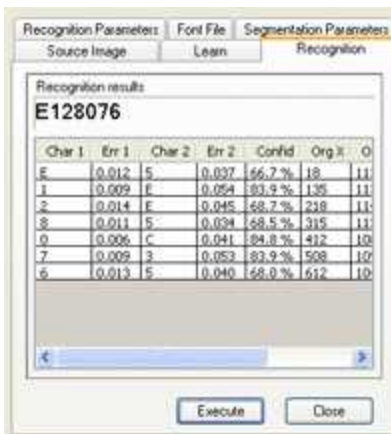
Objective

Following this tutorial, you will learn how to use EasyOCR to recognize characters, regarding to a specific font.

You'll need first to load a source image (step 1), and an EasyOCR font file (step 2). Then you'll perform the characters recognition (step 3).



Characters matching the font are automatically detected



Results after explicit recognition

Step 1: Load the source image

1. From the main menu, click EasyOCR, then New OCR Tool.
2. Keep the default variable name for the new OCR object, and click OK.
3. In the Source Image tab, click the Open icon of the Source Image area, and load the image file EasyOCR\FlatCable\FlatCable.tif.
4. Keep the default variable name for the new image object, and click OK.

Step 2: Load the font file

- In the Font File tab, click Load, and select the font file `EasyOCR\FlatCable\FlatCable.ocr`. In the image, the detected characters are highlighted in green.

Step 3: Recognize the characters

- In the Recognition tab, click Execute to trigger the recognition of the detected characters. The recognized characters appear in the Recognition results area. Further information about each character can be found in the table.

3. Code Snippets

3.1. Basic Types

Loading and Saving Images

Functional Guide | Reference: [Load](#), [Save](#), [SaveJpeg](#)

```

////////////////////////////////////
// This code snippet shows how to load and save an image. //
////////////////////////////////////

// Images constructor
EImageBW8 srcImage;
EImageBW8 dstImage;

// Load an image file
srcImage.Load("mySourceImage.bmp");

// ...

// Save the destination image into a file
dstImage.Save("myDestImage.bmp");

// Save the destination image into a jpeg file
// The default compression quality is 75
dstImage.Save("myDestImage.jpg");

// Save the destination image into a jpeg file
// set the compression quality to 50
dstImage.SaveJpeg("myDestImage50.jpg", 50);

```

Interfacing Third-Party Images

Functional Guide | Reference: [SetImagePtr](#)

```

////////////////////////////////////
// This code snippet shows how to link an Open eVision image //
// to an externally allocated buffer. //
////////////////////////////////////

// Images constructor
EImageBW8 srcImage;

// Size of the third-party image
int sizeX;
int sizeY;

//Pointer to the third-party image buffer
EBW8* imgPtr;

// ...

// Link the Open eVision image to the third-party image
// Assuming the corresponding buffer is aligned on 4 bytes
srcImage.SetImagePtr(sizeX, sizeY, imgPtr);

```

Retrieving Pixel Values

Functional Guide | Reference: [GetImagePtr](#)

```

////////////////////////////////////
// This code snippet shows the recommended method (fastest) //
// to access the pixel values in a BW8 image //
////////////////////////////////////

EImageBW8 img;

OEV_UINT8* pixelPtr;
OEV_UINT8* rowPtr;
OEV_UINT8 pixelValue;
OEV_UINT32 rowPitch;
int x, y;

rowPtr = reinterpret_cast <OEV_UINT8*>(img.GetImagePtr());
rowPitch = img.GetRowPitch();

for (y = 0; y < height; y++)
{
    pixelPtr = rowPtr;

    for (x = 0; x < width; x++)
    {
        pixelValue = *pixelPtr;

        // Add your pixel computation code here

        *pixelPtr = pixelValue;
        pixelPtr++;
    }

    rowPtr += rowPitch;
}

```

Importing Bitmap from the Resources

Functional Guide | Reference: [SetImagePtr](#)

```

////////////////////////////////////
// This code snippet shows how to import a bitmap from //
// the resources. //
////////////////////////////////////

// Get the bitmap
HBITMAP hbitmap = (HBITMAP)LoadImage(GetModuleHandle(NULL), MAKEINTRESOURCE(IDB_BITMAP), IMAGE_BITMAP, 0, 0, LR_
CREATEDIBSECTION);
BITMAP bitmap;
GetObject(hbitmap, sizeof(bitmap), (LPVOID)&bitmap);

int width = bitmap.bmWidth;
int height = bitmap.bmHeight;
UINT8* buffer = reinterpret_cast<UINT8*>(bitmap.bmBits);

EImageC24 image(width, height);

for (int y = 0; y < height; ++y)
{

```

```
// Copy the entire row
memcpy(image.GetImagePtr(0, height - 1 - y), buffer, 3 * width);
buffer += 3 * width;
}
```

ROI Placement

Functional Guide | Reference: [Attach](#), [SetPlacement](#)

```
////////////////////////////////////
// This code snippet shows how to attach an ROI to an image //
// and set its placement.                                     //
////////////////////////////////////

// Image constructor
EImageBW8 parentImage;

// ROI constructor
EROIBW8 myROI;

// ...

// Attach the ROI to the image
myROI.Attach(&parentImage);

//Set the ROI position
myROI.SetPlacement(50, 50, 200, 100);
```

Vector Management

Functional Guide | Reference: [Empty](#), [AddElement](#)

```
////////////////////////////////////
// This code snippet shows how to create a vector, fill it //
// and retrieve the value of a given element.               //
////////////////////////////////////

// EBW8Vector constructor
EBW8Vector ramp;

// Clear the vector
ramp.Empty();

// Fill the vector with increasing values
for(int i= 0; i < 28; i++)
{
    ramp.AddElement((EBW8)i);
}

// Retrieve the 9th element value
EBW8 value= ramp[9];
```

Exception Management

Functional Guide | Reference: [GetPixel](#), [What](#)

```
////////////////////////////////////
// This code snippet shows how to manage //
```



```
// Open eVision exceptions. //
////////////////////////////////////

try
{
    // Image constructor
    EImageC24 srcImage;

    // ...

    // Retrieve the pixel value at coordinates (56, 73)
    EC24 value= srcImage.GetPixel(56, 730);
}

catch(Euresys::Open_eVision_::EException exc)
{
    // Retrieve the exception description
    std::string error = exc.What();
}
```

3.2. EasyBarCode

Reading a Bar Code

Functional Guide | Reference: [Read](#)

```
////////////////////////////////////  
// This code snippet shows how to read a bar code //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// Bar code reader constructor  
EBarCode reader;  
  
// String for the decoded bar code  
std::string result;  
  
// ...  
  
// Read the source image  
result = reader.Read(&srcImage);
```

Reading a Bar Code Following a Given Symbology

Functional Guide | Reference: [SetAdditionalSymbologies](#), [SetVerifyChecksum](#), [Detect](#), [Decode](#), [GetNumDecodedSymbologies](#)

```
////////////////////////////////////  
// This code snippet shows how to enable a given symbology, //  
// enable the checksum verification, perform the bar code //  
// detection and retrieve the decoded string. //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// Bar code reader constructor  
EBarCode reader;  
  
// String for the decoded bar code  
std::string result;  
  
// ...  
  
// Disable all standard symbologies  
reader.SetStandardSymbologies(0);  
  
// Enable the Code32 symbology only  
reader.SetAdditionalSymbologies(ESymbologies_Code32);  
  
// Enable checksum verification  
reader.SetVerifyChecksum(true);  
  
// Detect all possible meanings of the bar code  
reader.Detect(&srcImage);  
  
// Retrieve the number of symbologies for
```

```
// which the decoding process was successful
int numDecoded = reader.GetNumDecodedSymbolologies();

if(numDecoded > 0)
{
    // Decode the bar code according to the Code32 symbology
    result = reader.Decode(ESymbolologies_Code32);
}
}
```

Reading a Bar Code of Known Location

Functional Guide | Reference: [SetKnownLocation](#), [SetCenterXY](#), [SetReadingSize](#)

```
////////////////////////////////////
// This code snippet shows how to specify the bar code //
// position and perform the bar code reading.          //
////////////////////////////////////

// Image constructor
EImageBW8 srcImage;

// Bar code reader constructor
EBarcode reader;

// String for the decoded bar code
std::string result;

// ...

// Disable automatic bar code detection
reader.SetKnownLocation(TRUE);

// Set the bar code position
reader.SetCenterXY(450.0f, 400.0f);
reader.SetSize(250.0f, 100.0f);
reader.SetReadingSize(100.0f, 0.5f);

// Read the bar code at the specified location
result = reader.Read(&srcImage);
```

Reading a Mail Bar Code

Functional Guide | Reference: [Read](#)

```
////////////////////////////////////
// This code snippet shows how to read Mail Barcodes //
// and retrieve the decoded data.                      //
////////////////////////////////////
// Image constructor
EImageBW8 srcImage;
// Mail barcode reader constructor
EMailBarcodeReader reader;

// Select expected symbolologies and orientations (optional)
reader.SetExpectedSymbolologies(...);
reader.SetExpectedOrientations(...);
// ...
// Read
std::vector<EMailBarcode> codes = reader.Read(srcImage);
// Retrieve the data included in found mail barcodes
for (unsigned int index= 0; index < codes.size(); index++)
```

```
{  
    std::string text = codes[index].GetText();  
    std::vector<EStringPair> components = codes[index]. GetComponentStrings();  
}
```

3.3. EasyMatrixCode

Automatic Reading

Functional Guide | Reference: [Read](#), [GetDecodedString](#)

```

////////////////////////////////////
// This code snippet shows how to read a data matrix code //
// and retrieve the decoded string. //
////////////////////////////////////

// Image constructor
EImageBW8 srcImage;

// Matrix code reader constructor
EMatrixCodeReader reader;

// Matrix code constructor
EMatrixCode mxCode;

// String for the decoded information
std::string result;

// ...

// Read the source image
mxCode = reader.Read(srcImage);

// Retrieve the decoded string
result = mxCode.GetDecodedString();

```

Reading with Prior Learning

Functional Guide | Reference: [SetLearnMaskElement](#), [Learn](#), [Read](#), [GetDecodedString](#)

```

////////////////////////////////////
// This code snippet shows how to learn a given data matrix //
// code type (except its flipping status), perform the //
// reading and retrieve the decoded string. //
////////////////////////////////////

// Images constructor
EImageBW8 model;
EImageBW8 srcImage;

// Matrix code reader constructor
EMatrixCodeReader reader;

// Matrix code constructor
EMatrixCode mxCode;

// String for the decoded information
std::string result;

// ...

// Tell the reader not to take the flipping into account when learning
reader.SetLearnMaskElement(ELearnParam_Flipping, false);

```

```
// Learn the model
reader.Learn(model);

// Read the source image
mxCode = reader.Read(srcImage);

// Retrieve the decoded string
result = mxCode.GetDecodedString();
```

Advanced Tuning of the Search Parameters

Functional Guide | Reference: [GetSearchParams](#), [ClearLogicalSize](#), [AddLogicalSize](#), [ClearFamily](#), [AddFamily](#), [Read](#), [GetDecodedString](#)

```
////////////////////////////////////
// This code snippet shows how to explicitly specify the data //
// matrix code logical size and family, perform the reading //
// and retrieve the decoded string. //
////////////////////////////////////

// Image constructor
EImageBW8 srcImage;

// Matrix code reader constructor
EMatrixCodeReader reader;

// Matrix code constructor
EMatrixCode mxCode;

// String for the decoded information
std::string result;

// ...

// Remove the default logical sizes
reader.GetSearchParams().ClearLogicalSize();

// Add the 5x5 and 7x7 logical sizes
reader.GetSearchParams().AddLogicalSize(ELogicalSize_5x5);
reader.GetSearchParams().AddLogicalSize(ELogicalSize_7x7);

// Remove the default families
reader.GetSearchParams().ClearFamily();

// Add the ECC050 family
reader.GetSearchParams().AddFamily(EFamily_ECC050);

// Read the source image
mxCode = reader.Read(srcImage);

// Retrieve the decoded string
result = mxCode.GetDecodedString();
```

Retrieving Print Quality Grading

Functional Guide | Reference: [SetComputeGrading](#), [GetAxialNonUniformityGrade](#), [GetContrastGrade](#), [GetPrintGrowthGrade](#), [GetUnusedErrorCorrectionGrade](#)

```
////////////////////////////////////  
// This code snippet shows how to read a data matrix code //  
// and retrieve its print quality grading. //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// Matrix code reader constructor  
EMatrixCodeReader reader;  
  
// Matrix code constructor  
EMatrixCode mxCode;  
  
// ...  
  
// Enable grading computation  
reader.SetComputeGrading(TRUE);  
  
// Read the source image  
mxCode = reader.Read(srcImage);  
  
// Retrieve the print quality grading  
int axialNonUniformityGrade= mxCode.GetAxialNonUniformityGrade();  
int contrastGrade= mxCode.GetContrastGrade();  
int printGrowthGrade= mxCode.GetPrintGrowthGrade();  
int unusedErrorCorrectionGrade= mxCode.GetUnusedErrorCorrectionGrade();
```

3.4. EasyQRCode

Automatic Reading of a QR Code

Functional Guide | Reference: [Read](#), [EQRCodeDecodedStream Class](#)

```
////////////////////////////////////  
// This code snippet shows how to read a QR code //  
// and retrieve the decoded data. //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// QR code reader constructor  
EQRCodeReader reader;  
  
// ...  
  
// Set the source image  
reader.SetSearchField(srcImage);  
  
// Read  
std::vector<EQRCode> qrCodes = reader.Read();
```

Retrieving Information of a QR Code

Functional Guide | Reference: [Read](#), [EQRCode Class](#)

```
////////////////////////////////////  
// This code snippet shows how to read a QR code //  
// and retrieve the associated information. //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// QR code reader constructor  
EQRCodeReader reader;  
  
// ...  
  
// Set the source image  
reader.SetSearchField(srcImage);  
// Read  
std::vector<EQRCode> qrCodes = reader.Read();  
  
// Retrieve version, model and position information  
// of the first QR code found, if one was found  
if (qrCodes.size() > 0)  
{  
    int version = qrCodes[0].GetVersion();  
    EQRCodeModel model = qrCodes[0].GetModel();  
    EQRCodeGeometry geometry = qrCodes[0].GetGeometry();  
}
```


Tuning the Search Parameters

Functional Guide | Reference: [Read](#), [GetDecodedString](#)

```
////////////////////////////////////  
// This code snippet shows how to read a QR code //  
// and retrieve the decoded data after setting a //  
// number of search parameters. //  
////////////////////////////////////  
  
// Image constructor  
EImageBW8 srcImage;  
  
// QR code reader constructor  
EQRCodeReader reader;  
  
// ...  
  
// Set the source image  
reader.SetSearchField(srcImage);  
  
// Set the search parameters  
reader.SetMaximumVersion(7);  
reader.SetMinimumIsotropy(0.9f);  
  
// Set the searched models  
std::vector<EQRCodeModel> models;  
models.push_back(EQRCodeModel_Model2);  
reader.SetSearchedModels(models);  
  
// Read  
std::vector<EQRCode> qrCodes = reader.Read();  
  
// Retrieve the decoded string in best guess mode of the first QR code found  
string decodedString = qrCodes[0].GetDecodedString(EByteInterpretationMode_Auto);
```

3.5. EasyOCR

Learning Characters

Functional Guide | Reference: [NewFont](#), [SetTextColor](#), [SetMinCharWidth](#), [SetMaxCharWidth](#), [SetMinCharHeight](#), [SetMaxCharHeight](#), [SetNoiseArea](#), [LearnPatterns](#), [BuildObjects](#), [FindAllChars](#), [Save](#)

```

////////////////////////////////////
// This code snippet shows how to learn characters //
// based on an image featuring a known text and //
// save the corresponding font file. //
////////////////////////////////////

// Image constructor
EImageBW8 srcImage;

// EOCR constructor
EOCR ocr;

// Text to be learned (all digits)
// Assuming the image contains this text
const std::string text= "0-23456789";

// ...

// Create a new fon
ocr.NewFont(8, ↵);

// Adjust the segmentation parameters
ocr.SetTextColor(EOCRColor_BlackOnWhite);
ocr.SetMinCharWidth(↵5);
ocr.SetMinCharWidth(50);
ocr.SetMinCharHeight(↵5);
ocr.SetMinCharHeight(75);
ocr.SetNoiseArea(↵5);

// Segment the characters
ocr.BuildObjects(&srcImage);
ocr.FindAllChars(&srcImage);

// Learn the characters
ocr.LearnPatterns(&srcImage, text, EOCClass_Digit);

// Save the font into a file
ocr.Save("myFont.ocr");

```

Recognizing Characters

Functional Guide | Reference: [Load](#), [Recognize](#)

```

////////////////////////////////////
// This code snippet shows how to load a font file, //
// perform a default character recognition operation //
// and perform a character recognition operation //
// using a class filter. //
////////////////////////////////////

```

```

// Image constructor
EImageBW8 srcImage;

// EOCR constructor
EOCR ocr;

// Load the font file
ocr.Load("myFont.ocr");

// ...

// Recognize the characters
std::string text= ocr.Recognize(&srcImage, 0, EOCClass_AllClasses);

// Alternatively
// Define the character filter (2 letters and 3 digits)
std::vector<UINT32> charFilter;
charFilter.push_back(EOCClass_UpperCase);
charFilter.push_back(EOCClass_UpperCase);
charFilter.push_back(EOCClass_Digit);
charFilter.push_back(EOCClass_Digit);
charFilter.push_back(EOCClass_Digit);

// Recognize the characters with class filtering
text= ocr.Recognize(&srcImage, 0, charFilter);

```

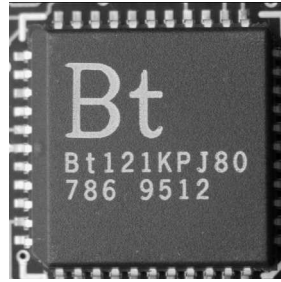
3.6. EasyOCR2

Detecting Characters

```

////////////////////////////////////
// This code snippet shows how to detect characters //
// in an image, using a few parameters and a topology //
////////////////////////////////////
// Load an Image
EImageBW8 image;
image.Load("image.tif");
// Attach a ROI to the image
EROIBW8 roi;
roi.Attach(&image, 50, 224, 340, 96);
// Create an EOCR2 instance
EOCR2 ocr2;
// Set the expected character sizes
ocr2.SetCharsWidthRange(EIntegerRange(25,25));
ocr2.SetCharsHeight(37);
// Set the text polarity, in this case WhiteOnBlack
ocr2.SetTextPolarity(EasyOCR2TextPolarity_WhiteOnBlack);
// Set the topology
ocr2.SetTopology(".{-0}\n.{3} .{4}");
// Detect the text in the image. The output Text structure contains:
// - an individual textbox for each character
// - an individual bitmap image for each character
// - a threshold value to binarize the bitmap image for each character
// All structured in a hierarchy with Lines -> Words -> Characters
EOCR2Text text = ocr2.Detect(roi);

```



The image used in this code snippet

Learning Characters

```

////////////////////////////////////
// This code snippet shows how to learn characters //
// based on an image featuring a known text and //
// save the corresponding character database //
////////////////////////////////////
// Load an Image
EImageBW8 image;
image.Load("image.tif");
// Attach a ROI to the image
EROIBW8 roi;
roi.Attach(&image, 50, 224, 340, 96);

// Create an EOCR2 instance
EOCR2 ocr2;

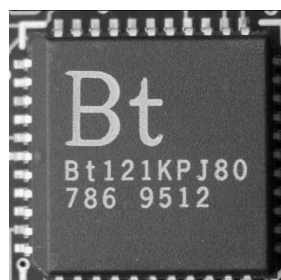
// Set the required parameters
ocr2.SetCharsWidthRange(EIntegerRange(25,25));
ocr2.SetCharsHeight(37);
ocr2.SetTextPolarity(EasyOCR2TextPolarity_WhiteOnBlack);
ocr2.SetTopology(".{-0}\n.{3} .{4}");

// Learn from the reference image:
// ↳ Detect the text in the image
EOCR2Text text = ocr2.Detect(roi);
// 2) Set the true values of the text
text.SetText("Bt-2-KPJ80\n786 95-2");
// 3) Add the characters to the character database
ocr2.Learn(text);

// Save the character database
ocr2.SaveCharacterDatabase("myDB.o2d");

// Alternatively, save the model file.
// This will store the character database and the parameter settings
ocr2.Save("myModel.o2m");

```



The image used in this code snippet

Reading Characters

Reading Using TrueType Fonts

```

////////////////////////////////////
// This code snippet shows how to //
// - create a character database from TrueType fonts //
// - read the text in an image //
////////////////////////////////////

// Load an image
EImageBW8 image;
image.Load("image.tif");

// Attach an ROI
EROIBW8 roi;
roi.Attach(&image, 50, 224, 340, 96);

// Create an EOCR2 instance
EOCR2 ocr2;

// Set the required parameters
ocr2.SetCharsWidthRange(EIntegerRange(25,25));
ocr2.SetCharsHeight(37);
ocr2.SetTopology("[LN]{_0}\nN{3} N{4}");
ocr2.SetTextPolarity(EasyOCR2TextPolarity_WhiteOnBlack);

// Add TrueType character to the character database
ocr2.AddCharactersToDatabase("C:\\Windows\\Fonts\\calibrib.ttf");
ocr2.AddCharactersToDatabase("C:\\Windows\\Fonts\\yugothb.ttc");

// Read text from the image
std::string result = ocr2.Read(roi);

```



The image used in this code snippet

Reading Using EOCR2 Character Database

```

////////////////////////////////////
// This code snippet shows how to //
// - load a pre-made character database //
// - read the text in an image //

```

```

////////////////////////////////////
// Load an image
EImageBW8 image;
image.Load("image.tif");

// Attach an ROI
EROIBW8 roi;
roi.Attach(&image, 50, 224, 340, 96);

// Create an EOCR2 instance
EOCR2 ocr2;

// Set the required parameters
ocr2.SetCharsWidthRange(EIntegerRange(25,25));
ocr2.SetCharsHeight(37);
ocr2.SetTopology("[LN]{-0}\nN{3} N{4}");
ocr2.SetTextPolarity(EasyOCR2TextPolarity_WhiteOnBlack);

// Add a pre-made character database to the EOCR2 instance
ocr2.AddCharactersToDatabase("myDB.o2d");

// Read text from the image
std::string result = ocr2.Read(roi);

```

Reading Using EOCR2 Model File

```

////////////////////////////////////
// This code snippet shows how to //
// - load a pre-made model file //
// - read the text in an image //
////////////////////////////////////

// Load an image
EImageBW8 image;
image.Load("image.tif");

// Attach an ROI
EROIBW8 roi;
roi.Attach(&image, 50, 224, 340, 96);

// Create an EOCR2 instance
EOCR2 ocr2;

// Load a pre-made model file, this will:
// - (re)set all parameters
// - add the character database in the model file to the EOCR2 instance
ocr2.Load("myModel.o2m");

// Read text from the image
std::string result = ocr2.Read(roi);

```